The two-scale approach to hydrodynamic limits for non-reversible dynamics

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Abstract

In [2], a new method to study hydrodynamic limits, called the two-scale approach, was developed for reversible dynamics. In this work, we generalize this method to a family of non-reversible dynamics. As an application, we obtain quantitative rates of convergence to the hydrodynamic limit for a weakly asymmetric version of the Ginzburg-Landau model endowed with Kawasaki dynamics. These results also imply local Gibbs behaviour, following a method of [1].

Keywords. Two-scale approach, hydrodynamic limits, non-reversible dynamics.

AMS subject classification. 60G99, 35K99.

1 Introduction

In this work, we are interested in generalizing the results of [2] on hydrodynamic limits to the case of weakly asymmetric interacting spin systems. We obtain quantitative rates of convergence to the hydrodynamic limit for such dynamics. Our main contribution is to show that we can control the effects of the antisymmetric component of the dynamic.

A typical result of convergence to the hydrodynamic limit consists in proving that, under a suitable time-space scaling and for nice initial conditions, a random system with a large number of particles behaves like a deterministic object, given as the solution of a partial differential equation. We refer to [4] for an overview of the field.

In [2], a new method to study such problems, called the two-scale approach, was developed. It consists in establishing estimates in Wasserstein distance between the distribution of the system and a well-chosen deterministic macroscopic state, given as the solution of a differential equation. The main elements are a coarse-graining argument and a logarithmic Sobolev inequality. It was applied to reversible dynamics of the form

$$dX_t = -A \nabla H(X_t) dt + \sqrt{2A} dW_t,$$

on some Euclidean space, where $A$ is a symmetric positive definite matrix, $H$ is the Hamiltonian and $W$ is a Wiener process. In the case where $A$ and $H$ correspond to the Ginzburg-Landau model endowed with Kawasaki dynamics, they obtained scaling limits of the form

$$\frac{\partial \rho}{\partial t} = \frac{\partial^2}{\partial \theta^2} \varphi'(\rho).$$

In this work, we add an extra term to the previous dynamic, and study

$$dX_t = -A \nabla H(X_t) dt - J \nabla H(X_t) dt + \sqrt{2A} dW_t,$$

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where $J$ is an antisymmetric matrix. This extra term makes the dynamic non-reversible, but does not modify the invariant measure. For the Ginzburg-Landau model, when $J$ is a discrete differentiation, we obtain a scaling limit of the form

$$\frac{\partial \rho}{\partial t} = \frac{\partial^2 \varphi'(\rho)}{\partial \theta^2} + \frac{\partial}{\partial \theta} \varphi'(\rho).$$

Our method is restricted to the case where the square of the antisymmetric part $-J^2$ is controlled by $A$ (in the sense of symmetric matrices). This is because if the antisymmetric component becomes dominant in the scaling limit, we would expect the limiting PDE to be hyperbolic (rather than parabolic), estimates in Wasserstein distances would not be adapted, and a different metric would be required.

These estimates in Wasserstein distance also allow us to study local Gibbs behaviour (which is stronger form of convergence) by using an interpolation inequality, following a method developed in [1]. Additionally, we obtain quantitative rates of convergence for the microscopic free energy to its scaling limit.

In general, hydrodynamic limit results for non-reversible dynamics are significantly harder to prove than in reversible situations. However, it turns out that the two-scale approach can be generalized under natural assumptions with fairly elementary arguments. The additional arguments for our main abstract result mostly rely on the Cauchy-Schwartz inequality and Gronwall-type estimates. We obtain easily-checkable and natural conditions for convergence to hold. Our method is illustrated with an application to a weakly asymmetric version of Kawasaki dynamics for a continuous spin system.

The plan of the paper is as follows: in Section 2, we present the framework and our main results. Section 3 contains the proofs of our results in the abstract setting. In section 4, we give the proofs of convergence to the hydrodynamic limit for the Ginzburg-Landau model endowed with a weakly asymmetric version of Kawasaki dynamics.

### Notations

- $C$ denotes a positive constant, which may vary from line to line, or even within a line.
- $\nabla$ is the gradient, Hess stands for Hessian, $|\cdot|$ is the norm and $\langle \cdot, \cdot \rangle$ is an inner product. If necessary, a subscript will indicate the space on which these are taken.
- $P^*$ is the adjoint of the operator $P$.
- $\Phi$ is the function defined by $\Phi(x) := x \log x$ on $\mathbb{R}_+$.
- $\text{Ent}_\mu(f) = \int f(\log f)\mu - (\int f\mu) \log (\int f\mu)$ is the entropy of the positive function $f$ with respect to the measure $\mu$.
- $Z$ is a constant enforcing unit mass for a probability measure.

### 2 Framework and main results

#### 2.1 Abstract setting

Let $X, Y$ be two Euclidean (or affine) spaces with $X \subset \mathbb{R}^N, Y \subset \mathbb{R}^M$ for some integers $N$ and $M$. We think of $X$ as the microscopic space and $Y$ as the macroscopic space. $N$ and $M$ can then be thought of as the size of the microscopic and macroscopic data respectively. Let $A$ and $J$ be respectively a positive definite symmetric and an anti-symmetric linear operator on $X$. Let $H : X \rightarrow \mathbb{R}$ be a given function. We consider the stochastic dynamics on $X$ that is given by the following stochastic differential equation (SDE)

$$dX_t = -A\nabla H(X_t) \, dt - J\nabla H(X_t) \, dt + \sqrt{2A} \, dW_t,$$
where \( W_t \) is a Wiener process, and \( \sqrt{A} \) is the square root of the matrix \( A \). When \( J \neq 0 \), this is a non-reversible process, and the Fokker-Planck equation associated to this SDE is
\[
\partial_t (f\mu) = \text{div}[\mu(A + J)\nabla f],
\]
where \( \mu \) is the invariant measure of the dynamics, which is
\[
\mu(dx) := \frac{1}{Z} \exp(-H(x))dx.
\]
Note that the addition of \( J \) does not change the invariant measure. As far as we know, every currently used method for proving hydrodynamic limit results relies on explicit knowledge of the invariant measure.

In the application we have in mind, which we shall present in the next section, \( A \) will be the discrete Laplacian, and \( J \) the discrete derivation.

We now introduce an abstract framework for the notion of coarse-graining operator. Let \( P: X \to Y \) be a linear operator such that
\[
NP^t = \text{id}_Y,
\]
where \( P^t \) is the adjoint operator of \( P \). We think of \( y = Px \) as the macroscopic state associated to the microscopic state \( x \). This operator induces a decomposition of the invariant measure into a macroscopic component and a fluctuation component. Let \( \pi(dy) = P_t\mu \) be the push-forward of \( \mu \) under the operator \( P \) and \( \mu(dx|y) \) be the conditional measure of \( \mu \) given \( Px = y \), i.e., for each \( y \), \( \mu(dx|y) \) is a probability measure on \( X \) and satisfies that for any test function \( g \)
\[
\int_X g(x)d\mu(x) = \int_Y \left( \int_{Px=y} g(x)\mu(dx|y) \right)\pi(dy).
\]

Applying the technique in [2], we show that under certain conditions, the macroscopic profile \( y = Px \), with law given by \( \mathcal{F}(t, y) = \int_{Px=y} f(t, x)\mu(dx) \), is close to the solution of the following differential equation
\[
\frac{d\eta}{dt} = -(\bar{A} + \bar{J})\nabla \mathcal{H}(\eta(t)).
\]

In this equation, \( \bar{A} \) is a symmetric, positive definite operator and \( \bar{J} \) is another operator on \( Y \) defined by
\[
\bar{A}^{-1} = PA^{-1}NP^t, \quad \bar{J} = \bar{A}PA^{-1}NJP^t,
\]
and \( \mathcal{H}: Y \to \mathbb{R} \) is the macroscopic Hamiltonian that satisfies
\[
\overline{\pi}(dy) = \exp(-N\overline{\mathcal{H}}(y))dy.
\]

In order to state the assumptions, we need to recall the definition of the Logarithmic Sobolev inequality (LSI). A probability measure \( \nu \in \mathcal{P}(X) \) is said to satisfy an LSI with constant \( \rho > 0 \) (abbreviation LSI(\( \rho \))) if, for any locally Lipschitz, nonnegative function \( f \in L^1(\nu) \),
\[
\int \Phi(f) d\nu - \Phi \left( \int f d\nu \right) \leq \frac{1}{2\rho} \int \frac{\|\nabla f\|^2}{f} d\nu.
\]

**Assumptions:** Throughout the paper, we assume that

(i) \( \kappa := \max_{x \in X} \{(\text{Hess } H(x) \cdot u, v), u \in \text{Ran}(NP^t), v \in \text{Ran}(\text{id}_X - NP^t), |u| = |v| = 1\} < \infty \);

(ii) There is \( \rho > 0 \) such that \( \mu(dx|y) \) satisfies LSI(\( \rho \)) for all \( y \);

(iii) There exist \( \lambda, \Lambda > 0 \) such that \( \lambda\text{id} \leq \text{Hess}\overline{\mathcal{H}} \leq \Lambda\text{id} \);
(iv) There is $\alpha > 0$ such that $\int_X |x|^2 f_\mu(dx) \leq \alpha N$;

(v) There is $\beta > 0$ such that $\inf_{y \in Y} H(y) \geq -\beta$;

(vi) There is $\gamma > 0$ such that for all $x \in X$,

$$|(id_X - NP^t P)x|^2 \leq \gamma M^{-2} \langle x, Ax \rangle_X;$$

(vii) There are constants $C_1$ and $C_2$ such that the initial datum satisfy

$$\int \Phi(f(0,x))\mu(dx) \leq C_1 N \quad \text{and} \quad \dot{H}(\eta_0) \leq C_2;$$

(viii) There is a $\tau > 0$ such that $A \geq \tau Id$;

(ix) $-J^2 \leq cA$;

(x) $J$ and $A$ commute.

Under these assumptions, we have the following bound on the (scaled) Wasserstein distance between $f_\mu$ and $\delta_{NP^t \eta}$ as well as the time-integrated Wasserstein distance between $\overline{T_R}$ and $\delta_\eta$.

**Theorem 2.1.** Let $\mu(dx) = Z^{-1} \exp(-H(x))\, dx$ be a probability measure on $X$, and let $P: X \to Y$ satisfy (3). Let $A: X \to X$ be a symmetric, positive definite operator, and $f(t, x)$ and $\eta(t)$ be the solutions of (2) and (5), with initial data $f(t, \cdot)$ and $\eta_0$ respectively. Suppose that the assumptions above hold. Define

$$\Theta(t) := \frac{1}{2N} \int_X (x - NP^t \eta(t)) \cdot A^{-1}(x - NP^t \eta(t)) f(t, x) \mu(dx).$$

Then for any $T > 0$, we have

$$\max \left\{ \sup_{0 \leq t \leq T} \Theta(t), \frac{\lambda}{8} \int_0^T \left( \int_Y |y - \eta(t)|^2 \overline{T(t, y)} \pi(dy) \right) dt \right\} \leq e^{\frac{4\gamma^2 T}{\lambda}} \left[ \Theta(0) + E(T, M, N) \right],$$

where $E(T, M, N) \to 0$ as $N \uparrow \infty, M \uparrow \infty, \frac{N}{M} \uparrow \infty$. More precisely,

$$E(T, M, N) = T \left( \frac{M}{N} \right) + \frac{4c\gamma^2 T}{\lambda} \left( \frac{\alpha + \frac{2C_1}{\rho}}{1} \right) \frac{1}{M} + C_1 \left( \frac{\gamma \kappa^2}{2\lambda^2 \rho^2} + \frac{2c\gamma^2}{\tau \lambda^2 \rho^2} + \frac{4\gamma \kappa^2}{\lambda^2} \right) \frac{1}{M^2}$$

$$+ \sqrt{2T \gamma} \left( \frac{\alpha + \frac{2C_1}{\rho}}{1} \right) \frac{1}{M} \left( 1 + \sqrt{\frac{C}{\tau} + \frac{\sqrt{2c\gamma}}{M}} \right) \sqrt{C_1}$$

$$+ \sqrt{2} \left( 1 + \sqrt{\frac{C}{\tau}} \right) (H(\eta_0) - H(\eta_T)) + CT(1 + e^{CT\overline{H}(\eta_0)})^{\frac{1}{2}} \frac{1}{M},$$

where

$$\hat{\rho} := \frac{1}{2} \left( \rho + \lambda + \frac{\kappa^2}{\rho} \right) - \sqrt{\left( \rho + \lambda + \frac{\kappa^2}{\rho} \right)^2 - 4\rho \lambda}.$$

**Remark 2.2** (Remarks on the assumptions). Assumptions (i) to (viii) are collected from [2] and [1]. Assumption (ix) means that the asymmetric effect is controlled by the symmetric one. Its main use is to rule out situations where the scaling limit is a hyperbolic equation (this would be the case for a continuous analog of the fully asymmetric exclusion process), which the two-scale approach doesn’t seem to handle. Assumption (x) is natural if we think of $J$ and $A$ as finite approximations of first and second derivatives operators, which is the application we have in mind. It could be replaced by an appropriate bound on the symmetric part of $PA^{-1}JNP^t$ (which is the macroscopic component of the commutator between $A^{-1}$ and $J$), and an additional bound of the
form $|\text{Tr}(PJA^{-1}NP)| \leq CM$. But since our proof is already fairly technical, and we do not have an application in mind that would warrant the greater generality, we decided to just assume that $A$ and $J$ commute, and simplify the proof. All these assumptions will be used in Lemma 3.4 to estimate the time derivative of $\Theta(t)$. In particular, (ii) and (vi) are used to handle the covariance and fluctuations terms respectively. Assumption (iii) is used to control the macroscopic terms, and implies a LSI for the coarse-grained measure $\bar{\mu}$.

The hydrodynamic limit is obtained as a consequence.

**Corollary 2.3.** Consider a sequence $\{X_\ell, Y_\ell, P_\ell, J_\ell, \mu_\ell, f_0, \eta_0, \ell\}$ satisfying the assumptions (i) to (x) with uniform constants $\kappa, \rho, \lambda, \Lambda, \alpha, \beta, \gamma, C_1, C_2$ and $c$. Suppose that

$$N_\ell \to \infty; \quad M_\ell \to \infty; \quad \frac{M_\ell}{N_\ell} \to 0.$$  

Further assume that

$$\lim_{\ell \to \infty} \frac{1}{N_\ell} \int (x - N_\ell P_\ell^t \eta_0, x) \cdot A_\ell^{-1}(x - N_\ell P_\ell^t \eta_0) f_0(t, x) \mu_\ell(dx) = 0.$$ 

Then, for any $T > 0$:

(a) The microscopic variables are close to the solution of (5) in the penalized norm induced by $A_\ell^{-1}$, uniformly in $t \in [0, T]$:

$$\lim_{\ell \to \infty} \sup_{0 \leq t \leq T} \frac{1}{N_\ell} \int (x - N_\ell P_\ell^t \eta_\ell) \cdot A_\ell^{-1}(x - N_\ell P_\ell^t \eta_\ell) f_\ell(t, x) \mu_\ell(dx) = 0;$$  

(b) The macroscopic variables are close to the solution of (5) in the strong $L^2(Y)$ norm, in a time-integrated sense:

$$\lim_{\ell \to \infty} \int_0^T \int |y - \eta_\ell|^2 \bar{f}(t, y) \bar{\mu}(dy) dt = 0.$$

Another topic of interest is whether the data behaves like a local Gibbs state.

**Definition 2.4.** The local Gibbs state with macroscopic profile $\eta \in Y$ is the probability measure on $X$ whose density with respect to $\mu$ is given by

$$G(x) \mu(dx) := \frac{1}{Z} \exp(NP^t \nabla \bar{H}(\eta) \cdot x) \mu(dx).$$

Such a probability measure is close (in Wasserstein distance) to the associated macroscopic profile $\eta$.

In [8], Yau showed that, if the initial data is close (in the sense of relative entropy) to a local Gibbs state, then this also holds at any positive time, for a time-dependent local Gibbs state. Since closeness in relative entropy is stronger (in the current setting) than closeness in Wasserstein distance (this is a consequence of Talagrand’s inequality, which is implied by the LSI, see for example [7]), the kind of results obtained with Yau’s method are stronger than those of the previous Corollary, but require a stronger assumption on the initial data.

In [5], it was shown that convergence in relative entropy actually holds at positive times, even if the initial data only converges in a weaker sense. In [1], the second author obtained a new proof of this fact in the reversible setting, using the two-scale approach. This method also yields quantitative rates of convergence in relative entropy. Now that we have generalized the two-scale approach to the non-reversible setting, the extension of the results of [1] follows.

**Theorem 2.5.** Let $G(t, x)$ be the time-dependent local Gibbs state associated to the solution $\eta$ of (5). Under our assumptions, the following holds:
(a) The relative entropy with respect to the local Gibbs state is controlled as follows:

\[
\int_0^T \frac{1}{N} \int \Phi \frac{f(t,x)}{G(t,x)} G(t,x) \mu(dx) dt = O \left( \sqrt{\Theta(0) + \frac{M}{N} + \frac{1}{M}} \right),
\]

where the actual constants in the bound (which can be made explicit) depend on \( T, \lambda, \Lambda, \alpha, \gamma, \rho, \kappa, \tau, c, C_1 \text{ and } C_2, \) but not on \( M \text{ and } N; \)

(b) The difference between the microscopic free energy and the free energy associated with the macroscopic profile \( \eta \) is bounded as follows:

\[
\int_0^T \left| \frac{1}{N} \int \Phi(f(t,x)) \mu(dx) - \bar{H}(\eta(t)) \right| dt = O \left( \sqrt{\Theta(0) + \frac{M}{N} + \frac{1}{M}} \right) + O \left( \frac{M}{N} \right) \times \max \left( \left| \log \left( \frac{\Gamma(Y, |\cdot| Y)^{2/(M-1)}}{\Lambda N} \right) \right|, \left| \log \left( \frac{\Gamma(Y, |\cdot| Y)^{2/(M-1)}}{\Lambda N} \right) \right| \right),
\]

where \( \Gamma(Y, |\cdot| Y) = \int \exp(-|y|^2_{\mathcal{Y}}/2) dy \) is the Gaussian integral on the (affine) space \( Y \) with respect to the norm \( |\cdot|_{\mathcal{Y}}. \)

### 2.2 Application to spin systems

We now give an application of Theorem 2.1 to a system of interacting continuous spins. We consider collections of \( N \) spins, in the space

\[
X_{N,m} := \left\{ x \in \mathbb{R}^N; \frac{1}{N} \sum_{i=1}^N x_i = m \right\},
\]

which we endow with the usual \( \ell^2 \) scalar product. The constraint \( N^{-1} \sum x_i = m \) corresponds to a constraint of fixed mean spin, that will be preserved by the dynamics.

The application we have in mind is when the matrices \( A \) and \( J \) are given by the \( N \)-dimensional matrices

\[
A = N^2 \begin{pmatrix}
2 & -1 & -1 & -1 \\
-1 & 2 & -1 & -1 \\
& \ddots & \ddots & \ddots \\
-1 & -1 & 2 & -1
\end{pmatrix}, \quad J = \frac{N}{2} \begin{pmatrix}
0 & 1 & -1 & -1 \\
-1 & 0 & 1 & -1 \\
& \ddots & \ddots & \ddots \\
1 & -1 & 0 & 1
\end{pmatrix}.
\]

As in [2], let

\[
H(x) := \sum_{i=1}^N \psi(x_i),
\]

where \( \psi : \mathbb{R} \longrightarrow \mathbb{R} \) satisfies the following assumptions:

\[
\psi(x) = \frac{1}{2} x^2 + \delta \psi(x); \quad \| \delta \psi \|_{\mathcal{C}^2} < \infty.
\]

This assumption will ensure that (iii) holds.

We consider the dynamic where \( A \) and \( J \) are given by (11)respectively. This corresponds to the system of \( N \) stochastic differential equations
\[ dX_i(t) = -N^2(2\psi(X_i) - \psi(X_{i+1}) - \psi(X_{i-1}))dt - \frac{N}{2}(\psi(X_{i+1}) - \psi(X_{i-1}))dt + N\sqrt{2}(dB_i^{t+1} - dB_i^t). \]

The index \( i \) goes from 1 to \( N \), and we impose periodic boundary conditions, that is \( N + 1 \equiv 1 \).

This is the dynamic studied in [3] and [2], to which we have added a weak asymmetric perturbation. This model is to the symmetric dynamic what the weakly asymmetric exclusion process is to the simple symmetric exclusion process, i.e., we have added an extra asymmetric term which has a scaling of lower order in \( N \).

Following [2], the macroscopic space is

\[ Y_{M,m} := \left\{ y \in \mathbb{R}^M; \frac{1}{N} \sum_{i=1}^M y_i = m \right\}, \]

which we endow with the \( L^2 \) scalar product

\[ \langle y, \tilde{y} \rangle_{Y} := \frac{1}{M} \sum_{i=1}^M y_i \tilde{y}_i. \]

The coarse graining operator \( P \) is defined as

\[ (Px)_i := \frac{1}{K} \sum_{j=(i-1)K+1}^{iK} x_j, \]

where \( K \) is an integer such that \( N = KM \). We can think of this coarse-graining operator as taking local averages of the microscopic profile over boxes of size \( K \). This operator does satisfy the relation \( PNP^t = id_Y \).

The coarse-grained Hamiltonian is given by

\[ \tilde{H}(y) = \frac{1}{M} \sum_{i=1}^M \psi_K(y_i) + \frac{1}{N} \log Z, \quad (14) \]

where

\[ \psi_K(m) := -\frac{1}{K} \log \int_{X_{K,m}} \exp \left( -\sum_{j=1}^K \psi(x_j) \right) dx. \quad (15) \]

A classical result of large deviations theory (see for example [2] for a proof) states that \( \psi_K \) is close, in a local sense, to the Cramer transform of \( \psi \), defined as

\[ \varphi(m) = \sup_{\sigma \in \mathbb{R}} \left\{ \sigma m - \log \int_{\mathbb{R}} \exp (\sigma x - \psi(x))dx \right\}. \quad (16) \]

More precisely, we have

\[ ||\psi_K - \varphi||_{C^2} \xrightarrow{K \to \infty} 0. \]

As a consequence, since \( \varphi \) is uniformly convex, and since \( \psi''_K \) uniformly converges to \( \varphi'' \), \( \psi_K \) is uniformly convex as soon as \( K \) is large enough. This shall allow us to apply the previous abstract theorem.

Without loss of generality, we shall assume in the sequel that \( m = 0 \), since it does not play a role in our estimates.

To study the scaling limit, we need to embed our spaces \( X_{N,m} \) into a single functional space. To a microscopic profile \( x \in X_{N,0} \), we associate the step function on the torus \( \bar{x} \), defined by
\( \bar{x}(\theta) := x_i \quad \forall \theta \in \left[ \frac{i-1}{N}, \frac{i}{N} \right] \). 

We endow the space \( L^2(\mathbb{T}) \) with the \( H^{-1} \) norm, defined by
\[
||w||_{H^{-1}}^2 = \int g^2 d\theta, \quad g' = w, \quad \int g d\theta = 0.
\]
The closure of the spaces \( X_N, 0 \) for this norm is the usual \( H^{-1} \) space of functions of average 0, which is the dual of the Sobolev space \( H^1 \) for the \( L^2 \) norm.

We can now state the hydrodynamic limit result we obtain for this model:

**Theorem 2.6.** Let \( A_\ell \) and \( J_\ell \) be given by (11). Assume that \( \psi \) satisfies (13). Let \( f(t, x) \) be a time-dependent probability density on \( (X_{N,0}, \mu_{N,0}) \) solving (2), with \( f(0, \cdot) = f_0 \) such that
\[
\int f_0 \log f_0 d\mu_{N,0} \leq CN,
\]
for some \( C > 0 \) and
\[
\lim_{N \to \infty} \int ||\bar{x} - \zeta_0||_{H^{-1}}^2 f_0(x) \mu_{N,0}(dx) = 0,
\]
for some initial macroscopic profile \( \zeta_0 \in L^2(\mathbb{T}) \). Then, for any \( T > 0 \), we have
\[
\lim_{N \to \infty} \sup_{0 \leq t \leq T} \int ||\bar{x} - \zeta(t, \cdot)||_{H^{-1}}^2 f(t, x) \mu_{N,0}(dx) = 0,
\]
where \( \zeta \) is the unique solution of
\[
\begin{cases}
\frac{\partial \zeta}{\partial t} = \frac{\partial^2}{\partial \theta^2} \varphi' (\zeta) + \frac{\partial}{\partial \theta} \varphi' (\zeta), \\
\zeta(0, \cdot) = \zeta_0,
\end{cases}
\]
where \( \varphi \) is the Cramér transform of \( \psi \), defined as (16).

We can also use the method of [1] to study local Gibbs behaviour, and convergence of the relative entropy.

**Theorem 2.7.** Under the same assumptions as in Theorem 2.6, the following holds:
\[
\int_0^T \int \phi \left( \frac{f_N(t, x)}{G_N(t, x)} \right) G_N(t, x) \mu_N(dx) dt \to 0,
\]
where \( G_N(t, \cdot) \) is the local Gibbs state given by \( \eta_N(t) \). As a consequence, we have convergence of the microscopic entropy to the hydrodynamic entropy, in a time-integrated sense:
\[
\int_0^T \left| \frac{1}{N} \int \phi \left( \frac{f_N(t, x)}{G_N(t, x)} \right) \mu_N(dx) - \left( \int_\mathbb{T} \varphi (\zeta(\theta, t)) d\theta - \varphi \left( \int_\mathbb{T} \zeta(t, \theta) d\theta \right) \right) \right| dt \xrightarrow{N \to \infty} 0.
\]

Moreover, convergence of \( \frac{1}{N} \int \phi \left( \frac{f_N(t, x)}{G_N(t, x)} \right) \mu_N(dx) \) to \( \int_\mathbb{T} \varphi (\zeta(\theta, t)) d\theta - \varphi \left( \int_\mathbb{T} \zeta(t, \theta) d\theta \right) \) holds uniformly on any time-interval \([\epsilon, T]\), for any \( 0 < \epsilon < T \).

Since deducing this result from Theorem 2.5 is nearly the same as in [1], we omit the proof. The only significant difference is proving that the solution \( \zeta \) of the hydrodynamic equation 18 is smooth on \([\epsilon, T]\), which is a well-known result in parabolic PDE theory (see for example [6]). Alternatively, it can be proven by a straightforward adaptation of the proof of Proposition 3.22 in [1].
3 Proof of the abstract results

In this section, we prove Theorem 2.1 and provide a sketch of proof of Theorem 2.5.

3.1 Proof of Theorem 2.1

Following the approach of [2], we prove Theorem 2.1 in three steps: first we differentiate with respect to time the (scaled) Wasserstein distance between $f(t)\mu$ and the macroscopic profile $\delta_{N P^t \eta(t)}$, and we split the expression into macroscopic components and fluctuations around the macroscopic profile. Then we derive an upper bound for the quantity we obtain, using assumption (iii) to control the macroscopic contribution and assumption (vi) to control fluctuations. Finally, we integrate in time and apply Gronwall’s Lemma to obtain the result.

**Lemma 3.1.** Let $\Theta$ be defined as in (8). We compute its time-derivative:

\[
\frac{d}{dt} \frac{1}{2N} \int_X (x - N P^t \eta(t)) \cdot A^{-1}(x - N P^t \eta(t)) f(t, x) \mu(dx)
\]

\[
= \frac{M}{N} - \int_Y (y - \eta) \cdot (\nabla_Y \bar{\eta}(y) - \nabla_Y \bar{\eta}(\eta)) \bar{f}(t, y) \bar{p}(dy)
\]

\[
- \int_Y P J A^{-1} N P^t (y - \eta) \cdot (\nabla_Y \bar{\eta}(y) - \nabla_Y \bar{\eta}(\eta)) \bar{f}(t, y) \bar{p}(dy)
\]

\[
- \int_Y (y - \eta) \cdot P \text{cov}_{\mu(dx|y)}(f, \nabla H) \bar{p}(dy)
\]

\[
- \frac{1}{N} \int_X (id_X - N P^t P)x \cdot \nabla f(t, x) \mu(dx)
\]

\[
+ \int \nabla \nabla_Y \bar{\eta}(\eta) \cdot PA^{-1}(id_X - N P^t P)x f \mu(dx)
\]

\[
+ \int_Y P J A^{-1} N P^t (y - \eta) \cdot P \text{cov}_{\mu(dx|y)}(f, \nabla H) \bar{p}(dy)
\]

\[
+ \int_Y P J A^{-1}(id_X - N P^t P)x \cdot P \nabla f(t, x) \mu(dx)
\]

\[
+ \frac{1}{N} \int_X (id_X - N P^t P)J A^{-1}(x - N P^t \eta) \cdot \nabla f(t, x) \mu(dx)
\]

\[
+ \int_X P A^{-1}(id_X - N P^t P)x \cdot \nabla \nabla_Y \bar{\eta}(\eta) f(t, x) \mu(dx).
\]

(21)

**Proof.** We have

\[
\frac{d}{dt} \frac{1}{2N} \int_X (x - N P^t \eta(t)) \cdot A^{-1}(x - N P^t \eta(t)) f(t, x) \mu(dx)
\]

\[
= \frac{2}{N} \int_X A^{-1}(x - N P^t \eta) \cdot (A + J) \nabla f \mu(dx) - \int P^t \frac{df}{dt} \cdot A^{-1}(x - N P^t \eta) f \mu(dx)
\]

\[
\leq \frac{2}{N} \int_X A^{-1}(x - N P^t \eta) \cdot A \nabla f \mu(dx) + \int \nabla \nabla_Y \bar{\eta}(\eta) \cdot PA^{-1}(x - N P^t \eta) f \mu(dx)
\]

\[
- \frac{1}{N} \int A^{-1}(x - N P^t \eta) \cdot J \nabla f \mu(dx) + \int A^{-1}(x - N P^t \eta) \cdot P^t \nabla \nabla_Y \bar{\eta}(\eta) f \mu(dx)
\]

\[
= (I) + (II) + (III) + (IV).
\]

(22)

We now use the decomposition $x = N P^t P x + (id_X - N P^t P)x$ to transform each term on the right hand side of (22). We need the following definition of the $\mu$-covariance of two functions $f, g \in L^2(\mu)$

\[
\text{cov}_{\mu}(f, g) = \int fg \, d\mu - \left( \int f \, d\mu \right) \left( \int g \, d\mu \right).
\]

(23)
The first two terms, \((I)\) and \((II)\), are already done in [2]. We repeat here for the sake of completeness.

\[
(I) = -\frac{1}{N} \int_X (x - NP^t\eta) \cdot \nabla f_\mu(dx)
= -\int_X P^t(Px - \eta) \cdot \nabla f_\mu(dx) - \frac{1}{N} \int (\text{id}_X - NP^tP)x \cdot \nabla f_\mu(dx). \tag{24}
\]

We now transform the first term in (24) using (4) and Lemma 21 in [2].

\[
-\int_X P^t(Px - \eta) \cdot \nabla f_\mu(dx) = -\int (Px - \eta) \cdot P\nabla f_\mu(dx)
\overset{(4)}{=} -\int_Y (y - \eta) \cdot P \int_{Px=y} \nabla f_\mu(dx|y) \mu(dy)
\overset{[2,(36)]}{=} -\frac{1}{N} \int (y - \eta) \cdot \nabla_Y \overline{\mu}(dy) - \int (y - \eta) \cdot P\text{cov}_\mu(dx|y)(f, \nabla H) \mu(dy)
\overset{(7)}{=} \frac{1}{N} \int \nabla_Y \overline{f}(y) \overline{\mu}(dy) - \int (y - \eta) \cdot \nabla_Y \overline{H}(y) \mu(dy) - \int (y - \eta) \cdot P\text{cov}_\mu(dx|y)(f, \nabla H) \mu(dy)
= \frac{\text{dim} Y}{N} \int (y - \eta) \cdot \nabla_Y \overline{H}(y) \overline{\mu}(dy) - \int (y - \eta) \cdot P\text{cov}_\mu(dx|y)(f, \nabla H) \mu(dy).
\]

We obtain

\[
(I) = \frac{\text{dim} Y}{N} \int (y - \eta) \cdot \nabla_Y \overline{H}(y) \overline{\mu}(dy) - \int (y - \eta) \cdot P\text{cov}_\mu(dx|y)(f, \nabla H) \mu(dy) - \frac{1}{N} \int (\text{id}_X - NP^tP)x \cdot \nabla f_\mu(dx). \tag{25}
\]

Now we proceed with \((II)\).

\[
(II) = \int \overline{\nabla_Y \overline{H}(\eta)} \cdot PA^{-1}NP^t(Px - \eta)f_\mu(dx) + \int \overline{\nabla_Y \overline{H}(\eta)} \cdot PA^{-1}(\text{id}_X - NP^tP)x f_\mu(dx)
\overset{(6)}{=} \int \nabla_Y \overline{H}(\eta) \cdot (Px - \eta)f_\mu(dx) + \int \overline{\nabla_Y \overline{H}(\eta)} \cdot PA^{-1}(\text{id}_X - NP^tP)x f_\mu(dx)
\overset{(4)}{=} \int_Y (y - \eta) \cdot \nabla_Y \overline{H}(\eta) \overline{\mu}(dy) + \int \overline{\nabla_Y \overline{H}(\eta)} \cdot PA^{-1}(\text{id}_X - NP^tP)x f_\mu(dx). \tag{26}
\]

Next, we continue with \((III)\).

\[
(III) = \frac{1}{N} \int JA^{-1}(x - NP^t\eta) \cdot \nabla f_\mu(dx)
\overset{1}{=} \frac{1}{N} \int PA^{-1}(x - NP^t\eta) \cdot NP\nabla f_\mu(dx) + \frac{1}{N} \int (\text{id}_X - NP^tP)JA^{-1}(x - NP^t\eta) \cdot \nabla f_\mu(dx)
\overset{1}{=} \frac{1}{N} \int PA^{-1}NP^t(Px - \eta) \cdot NP\nabla f_\mu(dx) + \frac{1}{N} \int PJA^{-1}(\text{id}_X - NP^tP)x \cdot NP\nabla f_\mu(dx)
+ \frac{1}{N} \int (\text{id}_X - NP^tP)JA^{-1}(x - NP^t\eta) \cdot \nabla f_\mu(dx).
\]

The first term on the right hand side of the expression above can be transformed further using
Lemma 3.2. as done for (I).

\[ \frac{1}{N} \int PJA^{-1}(x - NP^t \eta) \cdot NP \nabla f \mu(dx) = \frac{1}{N} \int Y \left( \int_{P_J = y} PJA^{-1}NP^t(y - \eta) \cdot NP \nabla f \mu(dx|y) \right) \pi(dy) \]

\[ = \frac{1}{N} \int Y PJA^{-1}NP^t(y - \eta) \cdot \left[ \nabla Y \mathcal{J}(y) + NP \text{cov}_{\mu(dx|y)}(f, \nabla H) \right] \pi(dy) \]

\[ = \frac{1}{N} \int Y PJA^{-1}NP^t(y - \eta) \cdot \nabla Y \mathcal{J}(y) \pi(dy) + \int Y PJA^{-1}NP^t(y - \eta) \cdot P \text{cov}_{\mu(dx|y)}(f, \nabla H) \pi(dy) \]

\[ = -\frac{\text{Tr}(PJA^{-1}NP^t)}{N} + \int Y PJA^{-1}NP^t(y - \eta) \cdot \nabla Y \mathcal{J}(y) \pi(dy) \]

\[ + \int Y PJA^{-1}NP^t(y - \eta) \cdot P \text{cov}_{\mu(dx|y)}(f, \nabla H) \pi(dy). \]

Since \( PJA^{-1}NP^t \) is anti-symmetric, \( \text{Tr}(PJA^{-1}NP^t)=0 \), and we obtain

\[ (III) = \int Y PJA^{-1}NP^t(y - \eta) \cdot \nabla Y \mathcal{J}(y) \pi(dy) \]

\[ + \int Y PJA^{-1}NP^t(y - \eta) \cdot P \text{cov}_{\mu(dx|y)}(f, \nabla H) \pi(dy) \]

\[ + \frac{1}{N} \int PJA^{-1}(id_X - NP^t P)x \cdot NP \nabla f \mu(dx) \]

\[ + \frac{1}{N} \int (id_X - NP^t P)JA^{-1}(x - NP^t \eta) \cdot \nabla f \mu(dx). \] (27)

Finally, we now transform (IV).

\[ (IV) = \int P A^{-1}NP^t(Px - \eta) \cdot \nabla \mathcal{J} \nabla \mathcal{J}(\eta) f \mu(dx) + \int P A^{-1}(id_X - NP^t P) \cdot \nabla \mathcal{J} \nabla \mathcal{J}(\eta) f \mu(dx) \]

\[ \overset{(4)}{=} \int Y P A^{-1}NP^t(y - \eta) \cdot \nabla \mathcal{J} \nabla \mathcal{J}(\eta) \pi(dy) + \int P A^{-1}(id_X - NP^t P) \cdot \nabla \mathcal{J} \nabla \mathcal{J}(\eta) f \mu(dx) \]

\[ \overset{(6)}{=} -\int Y PJA^{-1}NP^t(y - \eta) \cdot \nabla Y \mathcal{J}(\eta) \pi(dy) + \int P A^{-1}(id_X - NP^t P) \cdot \nabla Y \mathcal{J}(\eta) f \mu(dx). \] (28)

Substituting (25)-(28) into (22), we obtain (21) and the lemma is proven. \( \square \)

The following auxiliary lemma will be helpful in the sequel. The second and the third parts are respectively (54) and (52) in [2]; we state them here for the readers’ convenience.

**Lemma 3.2.** We have the following estimate

1. For every \( y \in Y \)

\[ |PJA^{-1}NP^t y|^2 \leq c |\mathcal{A}^{-1}_y y, y| \leq \frac{c}{\tau} |y|_Y^2. \] (29)

\[ \langle \mathcal{A}PJA^{-1}NP^t y, PJA^{-1}NP^t y \rangle \leq c |y|^2. \] (30)

2. For every \( x \in X \)

\[ (id_X - NP^t P)x \cdot \mathcal{A}^{-1}(id_X - NP^t P)x \leq \frac{\gamma}{M^2} |x|^2. \] (31)

3. It holds that

\[ |NP^t P \text{cov}_{\mu(dx|y)}(f, \nabla H)|^2 \leq \frac{\gamma^2 \kappa^2}{\mu^2} \frac{1}{M^2} \int \frac{1}{f^2} \nabla f \cdot \mathcal{A} \nabla f \mu(dx|y). \] (32)
Proof. We only need to prove the first part.

We start with (29). The first inequality is obtained using the assumption (2) and the fact that \( NP^t P \) is an orthogonal projection of \( X \) to \((\ker P)^\perp\) as follows.

\[
(PJA^{-1}NP^ty, PJA^{-1}NP^ty) = \frac{1}{N} \langle NP^t PJA^{-1}NP^ty, JA^{-1}NP^ty \rangle \\
\leq \frac{1}{N} \langle JA^{-1}NP^ty, JA^{-1}NP^ty \rangle \\
= -\frac{1}{N} \langle JP^2A^{-1}NP^ty, A^{-1}NP^ty \rangle \\
\leq \frac{c}{N} \langle A^{-1}NP^ty, NP^ty \rangle \quad \text{(used assumption (ix) here)} \\
= c \langle NP^{-1}P^ty, y \rangle \\
= c \langle A^{-1}y, y \rangle.
\]

Now we prove the second one. Since \( \tau \) is a lower bound on the spectral value of \( A \), \( \frac{1}{\tau} \) is an upper bound on that of \( A^{-1} \). Hence

\[
\langle A^{-1}y, y \rangle = \langle PA^{-1}NP^ty, y \rangle = \frac{1}{N} \langle A^{-1}NP^ty, NP^ty \rangle \leq \frac{1}{N\tau} \langle NP^ty, NP^ty \rangle = \frac{1}{\tau} |y|^2.
\]

Next, we prove (30). By duality, we have

\[
\langle APJA^{-1}NP^ty, PJA^{-1}NP^ty \rangle = \sup_z \{ 2\langle PJA^{-1}NP^ty, z \rangle - \langle A^{-1}z, z \rangle \} \\
\leq \sup_z \{ 2\langle y, PJA^{-1}NP^ty \rangle - c^{-1} |PJA^{-1}NP^ty|^2 \} \\
\leq \sup_z \{ 2\langle y, z \rangle - c^{-1} |z|^2 \} \\
\leq c |y|^2.
\]

\[
\langle A^{-1}y, y \rangle = (PA^{-1}NP^ty, y) = \frac{1}{N} \langle A^{-1}NP^ty, NP^ty \rangle \leq \frac{1}{N\tau} \langle NP^ty, NP^ty \rangle = \frac{1}{\tau} |y|^2.
\]

Lemma 3.3. If \( f(t, x) \) and \( \eta(t) \) satisfy the assumptions of theorem 2.1, then for any \( T < \infty \) we have

\[
\int_0^T \int \frac{1}{T} \nabla f \cdot A \nabla f(t, x) \mu(dx) dt = \int \Phi(f(0, x)) \mu(dx) - \int \Phi(f(T, x)) \mu(dx); \quad (33)
\]

\[
\int_0^T \langle \nabla \eta \nabla \eta, \nabla \eta \nabla \eta \rangle dt \leq 2(H(\eta_0) - H(\eta_T)) + C T(1 + e^{CT}H(\eta_0)), \quad (34)
\]

where \( C > 0 \) is a constant;

\[
\left( \int |x|^2 f(t, x) \mu(dx) \right)^{\frac{1}{2}} \leq \left( \int |x|^2 \mu(dx) \right)^{\frac{1}{2}} + \left( \frac{2}{\rho} \int \Phi(f(0, x)) \mu(dx) \right)^{\frac{1}{2}}. \quad (35)
\]

Proof. The proof of this lemma is similar to that of proposition 24 in [2]. We prove (33) first. We have

\[
\frac{d}{dt} \int \Phi(f(t, x)) \mu(dx) = \int (\log f + 1) \partial_t(f \mu) \\
= \int (\log f + 1) \text{div}(\mu(A + J) \nabla f) \\
= -\int (A + J) \nabla f \cdot \nabla f \mu(dx) \\
= -\int \frac{1}{T} A \nabla f \cdot \nabla f \mu(dx) \quad \text{(since \( J \) is anti-symmetric).} \quad (36)
\]
Thus (33) follows. Next we prove (34). We have

\[
\begin{align*}
\frac{d}{dt} \mathcal{H}(\eta(t)) &= \langle \dot{\eta}(t), \nabla_{\eta} \mathcal{H}(\eta(t)) \rangle \\
&\overset{(5)}{=} -\langle \mathcal{A}_Y \nabla_{\eta} \mathcal{H}(\eta), \mathcal{A}_Y \mathcal{H}(\eta) \rangle - \langle \mathcal{L}_{\nabla_{\eta} \mathcal{H}(\eta)} \mathcal{A}_Y, \mathcal{A}_Y \mathcal{H}(\eta) \rangle \\
&= -\langle \mathcal{A}_Y \nabla_{\eta} \mathcal{H}(\eta), \mathcal{A}_Y \mathcal{H}(\eta) \rangle - \langle \mathcal{A}_Y \mathcal{H}(\eta), \mathcal{A}_Y \mathcal{H}(\eta) \rangle \\
&\leq -\frac{1}{2} \langle \mathcal{A}_Y \mathcal{H}(\eta), \mathcal{A}_Y \mathcal{H}(\eta) \rangle - \langle \mathcal{A}_Y \mathcal{H}(\eta), \mathcal{A}_Y \mathcal{H}(\eta) \rangle \\
&\leq \frac{c}{2} \nabla_{\eta} \mathcal{H}(\eta) \rangle^2 - \frac{1}{2} \langle \mathcal{A}_Y \mathcal{H}(\eta), \mathcal{A}_Y \mathcal{H}(\eta) \rangle.
\end{align*}
\]

In this computation, we used the assumption that \(A\) and \(J\) commute. Therefore

\[
\begin{align*}
\frac{d}{dt} \mathcal{H}(\eta(t)) + \frac{1}{2} \langle \mathcal{A}_Y \mathcal{H}(\eta), \mathcal{A}_Y \mathcal{H}(\eta) \rangle &\leq \frac{c}{2} \nabla_{\eta} \mathcal{H}(\eta) \rangle^2 \\
&\leq C(|\eta|^2 + 1) \leq C(\mathcal{H}(\eta) + 1).
\end{align*}
\]

In the above estimate, \(C > 0\) is a general constant. Note that we have used assumption (iii). The above Gronwall-type inequality implies that for every \(t \geq 0\), we have \(\mathcal{H}(\eta(t)) \leq e^{CT} \mathcal{H}(\eta_0) + 1\), and

\[
\begin{align*}
\int_0^T \langle \mathcal{A}_Y \mathcal{H}(\eta), \mathcal{A}_Y \mathcal{H}(\eta) \rangle \mathcal{P} dt &\leq C e^{CT} (\mathcal{H}(\eta_0) + 1).
\end{align*}
\]

According to Lemma 26 in [2], since \(\mu\) satisfies LSI(\(\rho\)), we have

\[
\left( \int |x|^2 f(t,x)\mu(dx) \right)^{1/2} \leq \left( \int |x|^2 \mu(dx) \right)^{1/2} + \left( \frac{c}{\tau} \int \Phi(f(t,x)) \mu(dx) \right)^{1/2}.
\]

By (36), \(\int \Phi(f(t,x)) \mu(dx)\) is non-increasing in \(t\), and (35) immediately follows. \(\Box\)

**Lemma 3.4.** We have the following estimate

\[
\begin{align*}
\frac{d}{dt} \Theta(t) - \frac{8c \lambda^2}{\lambda} \Theta(t) &+ \frac{\lambda}{8} \int |y - \eta|^2 \mathcal{P}(dy) \\
&\leq \frac{M}{N} + \frac{4c \gamma \rho^2 M^2}{2 \lambda \rho^2 M^2} \int |x|^2 \mu(dx) \\
&+ \left( \frac{\gamma \rho^2}{2 \lambda \rho^2 M^2} + \frac{2c \gamma \rho^2}{\tau \lambda \rho^2 M^2} + \frac{4c \gamma}{\lambda \rho^2 M^2} \right) \int \frac{1}{N f} \nabla f \cdot \nabla \mu(dx) \\
&+ \left( 1 + \sqrt{\frac{c}{\tau}} \right) \left( \int \frac{1}{N f} \nabla f \cdot \nabla \mu(dx) \right)^{1/2} \\
&+ \left( 1 + \sqrt{\frac{c}{\tau}} \right) \left( \int \mathcal{A}_Y \mathcal{H}(\eta), \mathcal{A}_Y \mathcal{H}(\eta) \right)^{1/2}.
\end{align*}
\]

*Proof.* We estimate each term in (21). The 2nd, 4th and 5th terms are already estimated in [2] (these are respectively equations (50), (53) and (55) in [2]). We get

\[
\begin{align*}
- \int \langle y - \eta \rangle \cdot \langle \nabla_{\eta} \mathcal{H}(y) \rangle \mathcal{P}(dy) &\leq -\lambda \int |y - \eta|^2 \mathcal{P}(dy), \\
\left| \int \langle y - \eta \rangle \cdot P \text{cov}_{\mu(dx)}(f, \nabla \mathcal{H}) \mathcal{P}(dy) \right| &\leq \frac{\gamma \rho^2}{2 \lambda \rho^2 M^2} \int \frac{1}{N f} \nabla f \cdot \nabla \mu(dx) + \frac{\lambda}{2} \int |y - \eta|^2 \mathcal{P}(dy), \\
\left| \frac{1}{N} \int \langle x \rangle \cdot \nabla \mu(dx) \right| &\leq \frac{\gamma}{M^2} \int \frac{1}{N f} \nabla f \cdot \nabla \mu(dx) \cdot \int \frac{1}{N} \langle x \rangle^2 f \mu(dx) \right)^{1/2}.
\end{align*}
\]
We estimate the 3rd term. Since
\[
|PJA^{-1}NP^t(y - \eta)| \cdot |\nabla_Y \overline{H}(y) - \nabla_Y \overline{H}(\eta)| \leq A|y - \eta| \cdot |PJA^{-1}NP^t(y - \eta)|
\]
(29)
\[
A|y - \eta| \sqrt{c(A^{-1}(y - \eta), y - \eta)}
\]
\[
\leq \frac{\lambda}{8}|y - \eta|^2 + \frac{2c\lambda^2}{\lambda}(A^{-1}(y - \eta), y - \eta),
\]
we have
\[
\int Y PJA^{-1}NP^t(y - \eta) \cdot (\nabla_Y \overline{H}(y) - \nabla_Y \overline{H}(\eta)) \mathcal{P}(dy)
\]
\[
\leq \frac{\lambda}{8} \int Y |y - \eta|^2 \mathcal{P}(dy) + \frac{2c\lambda^2}{\lambda} \int Y (A^{-1}(y - \eta), y - \eta) \mathcal{P}(dy)
\]
\[
= \frac{\lambda}{8} \int Y |y - \eta|^2 \mathcal{P}(dy) + \frac{2c\lambda^2}{\lambda} \int \int X (A^{-1}NP^t(Px - \eta), NP^t(Px - \eta)) f_\mu(dx)
\]
\[
\leq \frac{\lambda}{8} \int Y |y - \eta|^2 \mathcal{P}(dy) + \frac{2c\lambda^2}{\lambda} \int \int X (A^{-1}(x - NP^t\eta), (x - NP^t\eta)) f_\mu(dx)
\]
\[
+ \frac{2c\lambda^2}{\lambda} \int X (A^{-1}(id_X - NP^tP)x, (id_X - NP^tP)x) f_\mu(dx)
\]
\[
\leq \frac{\lambda}{8} \int Y |y - \eta|^2 \mathcal{P}(dy) + \frac{8c\lambda^2}{\lambda} \Theta(t) + \frac{4c\lambda^2}{\lambda} \int \int X (|x|^2 f_\mu(dx)),
\]
(41)
where we used (31) to get the last inequality. Next we estimate the 6th term.
\[
\int Y PJA^{-1}NP^t(id_X - NP^tP)x f_\mu(dx)
\]
\[
= \int P^t A^{-1}NP^t \nabla_Y \overline{H}(\eta) \cdot A^{-1}(id_X - NP^tP)x f_\mu(dx)
\]
\[
\leq \left( \int P^t A^{-1}NP^t \nabla_Y \overline{H}(\eta) f_\mu(dx) \right)^\frac{1}{2} \left( \int (id_X - NP^tP)x \cdot A^{-1}(id_X - NP^tP)x f_\mu(dx) \right)^\frac{1}{2}.
\]
Since
\[
P^t A^{-1}NP^t \nabla_Y \overline{H}(\eta) = A \nabla_Y \overline{H}(\eta) \cdot P^{-1} A^{-1}NP^t \nabla_Y \overline{H}(\eta) = \nabla_Y \overline{H}(\eta) \cdot \nabla_Y \overline{H},
\]
and from (31), we have
\[
\int Y (\nabla_Y \overline{H}(\eta) \cdot P^{-1} A^{-1}NP^t \nabla_Y \overline{H}(\eta)) f_\mu(dx) \leq \left( \int (\nabla_Y \overline{H}(\eta) \cdot \nabla_Y \overline{H}(\eta)) f_\mu(dx) \right)^\frac{1}{2} \left( \frac{\gamma}{NM^2} \int |x|^2 f_\mu(dx) \right)^\frac{1}{2}.
\]
(42)
Next, we estimate the 7th term.
\[
\left| \int Y PJA^{-1}NP^t(y - \eta) \cdot P\text{cov}_{(dx|y)}(f, \nabla H) \mathcal{P}(dy) \right|
\]
\[
\leq \left( \int Y PJA^{-1}NP^t(y - \eta)|^2 \mathcal{P}(dy) \cdot \int \int Y P\text{cov}_{(dx|y)}(f, \nabla H)|^2 \mathcal{P}(dy) \right)^\frac{1}{2}
\]
(29),(32)
\[
\leq \left( \frac{2c\gamma^2}{\tau} \int |y - \eta|^2 \mathcal{P}(dy) \int \int \frac{1}{Nf} \nabla f \cdot A \nabla f \mu(dx) \right)^\frac{1}{2}
\]
\[
\leq \frac{2c\gamma^2}{\tau \lambda \rho^2 M^2} \int \int \frac{1}{Nf} \nabla f \cdot A \nabla f \mu(dx) + \frac{\lambda}{8} \int |y - \eta|^2 \mathcal{P}(dy).
\]
(43)
For the 8th term, we have
\[
\int PJA^{-1} (\text{id}_X - NP^t P)x \cdot P \nabla f_\mu(dx) = \frac{1}{N} \int NP^t PJA^{-1} (\text{id}_X - NP^t P)x \nabla f_\mu(dx)
\]
\[
\leq \left( \int \frac{1}{N} NP^t PJA^{-1} (\text{id}_X - NP^t P)x \cdot A^{-1} NP^t PJA^{-1} (\text{id}_X - NP^t P)x f_\mu(dx) \right)^\frac{1}{2} \left( \int \frac{1}{NJ} \nabla f \cdot A \nabla f_\mu(dx) \right)^\frac{1}{2}.
\]
Since
\[
\langle NP^t PJA^{-1} (\text{id}_X - NP^t P)x, A^{-1} NP^t PJA^{-1} (\text{id}_X - NP^t P)x \rangle
\]
\[
\leq \frac{1}{\tau} \langle NP^t PJA^{-1} (\text{id}_X - NP^t P)x, NP^t PJA^{-1} (\text{id}_X - NP^t P)x \rangle
\]
\[
\leq \frac{1}{\tau} \langle JA^{-1} (\text{id}_X - NP^t P)x, JA^{-1} (\text{id}_X - NP^t P)x \rangle
\]
\[
= \frac{1}{\tau} \langle -J^2 A^{-1} (\text{id}_X - NP^t P)x, A^{-1} (\text{id}_X - NP^t P)x \rangle
\]
\[
\leq \frac{c}{\tau} \langle (\text{id}_X - NP^t P)x, A^{-1} (\text{id}_X - NP^t P)x \rangle
\]
\[
\leq \frac{c\gamma}{\tau M^2} |x|^2,
\]
we obtain
\[
\int PJA^{-1} (\text{id}_X - NP^t P)x \cdot P \nabla f_\mu(dx) \leq \left( \frac{c\gamma}{\tau M^2} \int \frac{1}{N} |x|^2 f_\mu(dx) \cdot \int \frac{1}{NJ} \nabla f \cdot A \nabla f_\mu(dx) \right)^\frac{1}{2}. \tag{44}
\]
Next we estimate the 9th term. Set \( z = JA^{-1} (x - NP^t \eta) \). We have
\[
\frac{1}{N} \int (\text{id}_X - NP^t P)JA^{-1} (x - NP^t \eta) \cdot \nabla f_\mu(dx) = \frac{1}{N} \int (\text{id}_X - NP^t P)z \cdot \nabla f_\mu(dx)
\]
\[
\leq \left( \int \frac{1}{N} (\text{id}_X - NP^t P)z \cdot A^{-1} (\text{id}_X - NP^t P)zf_\mu(dx) \int \frac{1}{NJ} \nabla f \cdot A \nabla f_\mu(dx) \right)^\frac{1}{2}
\]
\[
\leq \left( \frac{\gamma}{M^2} \int \frac{1}{NJ} \nabla f \cdot A \nabla f_\mu(dx) \int \frac{1}{N} |z|^2 f_\mu(dx) \right)^\frac{1}{2}.
\]
We estimate the second integral inside the parentheses. It holds that
\[
|z|^2 = \langle JA^{-1} (x - NP^t \eta), JA^{-1} (x - NP^t \eta) \rangle = \langle -J^2 A^{-1} (x - NP^t \eta), A^{-1} (x - NP^t \eta) \rangle
\]
\[
\leq c(A^{-1} (x - NP^t \eta), x - NP^t \eta)
\]
\[
\leq 2c \left( A^{-1} NP^t (PX - \eta), NP^t (PX - \eta) + A^{-1} (\text{id}_X - NP^t P)x, (\text{id}_X - NP^t P)x \right)
\]
\[
\leq 2c \left( \frac{1}{\tau} |NP^t (PX - \eta)|^2 + \frac{\gamma}{M^2} |x|^2 \right) = 2c \left( \frac{\tau}{\gamma} |PX - \eta|^2 + \frac{\gamma}{M^2} |x|^2 \right).
\]
Therefore,
\[
\frac{1}{N} \int (\text{id}_X - NP^t P)JA^{-1} (x - NP^t \eta) \cdot \nabla f_\mu(dx)
\]
\[
\leq \left( \frac{\gamma}{M^2} \int \frac{1}{NJ} \nabla f \cdot A \nabla f_\mu(dx) \right)^\frac{1}{2} \left( \frac{2c}{\tau} \int |y - \eta|^2 \tilde{\mathcal{P}}(dy) + \frac{2c\gamma}{M^2} \int |y|^2 f_\mu(dx) \right)^\frac{1}{2}
\]
\[
\leq \frac{4c\gamma}{M^2 \lambda^2} \int \frac{1}{NJ} \nabla f \cdot A \nabla f_\mu(dx) + \frac{\lambda}{8} \int |y - \eta|^2 \tilde{\mathcal{P}}(dy)
\]
\[
+ \left( \frac{\gamma}{M^2} \int \frac{1}{NJ} \nabla f \cdot A \nabla f_\mu(dx) \right)^\frac{1}{2} \left( \frac{2c\gamma}{M^2} \int |y|^2 f_\mu(dx) \right)^\frac{1}{2}. \tag{45}
\]
Finally, we estimate the 10th term. Since
\[ \langle PA^{-1}NP^t \nabla H(\eta), J\nabla H(\eta) \rangle = \langle PA^{-1}NP^t \nabla H(\eta), \tilde{A}PA^{-1}NP^t \nabla H(\eta) \rangle \]
we have
\[ \int A^{-1}(\text{id}_X - NP^tP)x \cdot P^t\nabla_y \tilde{H}(\eta) f\mu(dx) \]
\[ \leq \left( \int P^t\nabla_y \tilde{H}(\eta) \cdot A^{-1}NP^t\nabla_y \tilde{H}(\eta) f\mu(dx) \right)^{\frac{1}{2}} \left( \int \frac{1}{N}(\text{id}_X - NP^tP)x \cdot A^{-1}(\text{id}_X - NP^tP)x f\mu(dx) \right)^{\frac{1}{2}} \]
\[ \leq \left( \frac{C}{\tau} \nabla \tilde{H}(\eta) \cdot \nabla \tilde{H}(\eta) \right)^{\frac{1}{2}} \left( \frac{\gamma}{NM^2} \int |x|^2 f\mu(dx) \right)^{\frac{1}{2}} . \quad (46) \]

Summing up from (38) to (46), we obtain (37).

**Proof of Theorem 2.1.** Denote by $R(t)$ the right hand side of (37). Set $D = \frac{2c\lambda^2}{\tau}$. For any $0 < t \leq T$, we have
\[ \frac{d}{dt} \left( e^{-DT} \Theta(t) \right) + e^{-DT} \frac{\lambda}{8} \int |y - \eta|^2 f\tilde{\mu}(dy) \leq \frac{d}{dt} \left( e^{-DT} \Theta(t) \right) + e^{-DT} \frac{\lambda}{8} \int |y - \eta|^2 f\tilde{\mu}(dy) \leq e^{-DT} R(t) \leq R(t) . \quad (47) \]
Integrating (47) with respect to time, for any $0 < t \leq T$, we have
\[ e^{-DT} \Theta(t) + \frac{\lambda}{8} e^{-DT} \int_0^T |y - \eta|^2 f\tilde{\mu}(dy) \leq e^{-DT} \Theta(t) + \frac{\lambda}{8} e^{-DT} \int_0^T \int |y - \eta|^2 f\tilde{\mu}(dy) dt \leq \Theta(0) + \int_0^T R(t) dt . \quad (48) \]
It follows that for any $T > 0$
\[ \max \left\{ \sup_{t \in (0,T)} \Theta(t), \frac{\lambda}{8} \int_0^T \int |y - \eta|^2 f\tilde{\mu}(dy) \right\} \leq e^{\frac{\lambda}{8}T} \left( \Theta(0) + \int_0^T R(t) dt \right) . \quad (49) \]
It remains to take care of each term in the right hand side of (49). Recall that $R$ is the right hand side of (37). Let $a = 1 + \sqrt{\frac{\tau}{\lambda^2}}$, $b = 1 + \sqrt{\frac{\tau}{\gamma}}$. We have the following estimates
\[ \int_0^T \int \frac{1}{N} |x|^2 f(t, x) \mu(dx) dt \leq 2 \left( \alpha + \frac{2C_1}{\rho} \right) T ; \]
\[ \int_0^T \int \frac{1}{N} \nabla \cdot A \nabla f \mu(dx) dt \leq C_1 ; \]
\[ \int_0^T \left( \int \frac{1}{N} |x|^2 f \mu(dx) \right)^{\frac{1}{2}} \left( a \left( \int \frac{1}{N} \nabla f \cdot A \nabla f \mu(dx) \right) + b \left( \tilde{A} \nabla_y \tilde{H}(\eta) \cdot \nabla_y \tilde{H}(\eta) \right) \right) dt \]
\[ \leq \sqrt{2T} \left( a + \frac{2C_1}{\rho} \right)^{\frac{1}{2}} \left( a \sqrt{C_1} + \sqrt{2b \left( H(\eta_0) - H(\eta_T) \right)} + CT \left(1 + e^{CT \tilde{H}(\eta_0)} \right) \right) . \]
Substituting these estimate to (49) concludes the proof of Theorem 2.1. \(\square\)
3.2 Sketch of proof of Theorem 2.5

In this section, we give the main arguments of the proof of Theorem 2.5, which exactly follows the method of [1]. Recall that the local Gibbs state is given by $G(x)\mu(dx)$, where $G(x) = Z^{-1} \exp(NP\bar{H}(\eta) \cdot x)$.

- First, we decompose the relative entropy with respect to the local Gibbs state into a macroscopic component and a fluctuations component. Since $G(x)$ only depends on the macroscopic profile $y = P x$, we have

$$\text{Ent}_{G\mu}(f\mu) = \text{Ent}_{\bar{G}\bar{\mu}}(\bar{f}\bar{\mu}) + \int_Y \text{Ent}_{\mu(dx|y)}(f\mu)G(y)\bar{\mu}(dy).$$

- The fluctuations component $\int_0^T \int_Y \text{Ent}_{\mu(dx|y)}(f\mu)G(y)\bar{\mu}(dy)dt$ can be bounded using the logarithmic Sobolev inequality for $\mu(dx|y)$, assumption (vi) and (33) in Lemma 3.3.

- For the macroscopic component, since $\bar{G}\bar{\mu}$ is log-concave, we can use the HWI inequality of [7], which states that

$$\text{Ent}_{\bar{G}\bar{\mu}}(\bar{f}\bar{\mu}) \leq W_2^2(\bar{f}\bar{\mu},\bar{\mu}) \sqrt{I_{\bar{G}\bar{\mu}}(\bar{f}\bar{\mu})},$$

where the Wasserstein distance $W_2$ is taken with respect to the norm $|\cdot|_Y$, and $I$ is the Fisher information

$$I_{\bar{G}\bar{\mu}}(\bar{f}\bar{\mu}) := \int \frac{|\nabla (\bar{f}/\bar{G})|^2}{\bar{f}/\bar{G}} \bar{G}d\bar{\mu}.$$

As a consequence, to obtain convergence in relative entropy, we only require convergence in Wasserstein distance and a bound on the Fisher information.

- We already have a bound on $\int_0^T W_2^2(\bar{f}\bar{\mu},\delta_{\eta(t)})^2 dt$ from Theorem 2.1. Moreover,

$$W_2^2(\bar{G}\bar{\mu},\delta_\eta)^2 \leq \frac{M}{\lambda N}$$

by Proposition 4.1 of [1]. A bound on $\int_0^T W_2^2(\bar{f}\bar{\mu},\bar{G}\bar{\mu})dt$ immediately follows from the triangle inequality.

- Finally, the time-integral of the Fisher information can be bounded using the bounds on the entropy production of Lemma 3.3. This concludes the proof of (a).

- (b) can be deduced from (a) using elementary inequalities and the bound

$$\left| \frac{1}{N} \int \Phi(G^n)d\mu - \bar{H}(\eta) \right| \leq \frac{(M - 1)}{2N} \max \left( \log \left( \frac{\Gamma(Y,|\cdot|_Y)^{2/(M - 1)}}{\Lambda N} \right), \log \left( \frac{\Gamma(Y,|\cdot|_Y)^{2/(M - 1)}}{\lambda N} \right) \right) + \sqrt{\frac{M}{\lambda N} |\nabla \bar{H}(\eta)|_Y},$$

which was proven in Proposition 4.1 of [1].

4 Application to weakly asymmetric Kawasaki dynamics

In this section, we prove Theorem 2.6. First, we give a precise definition of the notion of weak solution to the limiting equation (18).
Definition 4.1. $\zeta = \zeta(t, \theta)$ is called a weak solution of (18) on $[0, T] \times \mathbb{T}$ if
\[ \zeta \in L^\infty_t(L^2_\theta), \quad \frac{\partial \zeta}{\partial t} \in L^2_t(H^{-1}_\theta), \quad \varphi'(\zeta) \in L^2_t(L^2_\theta), \] (50)
and
\[ \left\langle g, \frac{\partial \zeta}{\partial t} \right\rangle_{H^{-1}} = -\int_{\mathbb{T}} g \varphi'(\zeta) \, d\theta + \int_{\mathbb{T}} G \varphi'(\zeta) \, d\theta, \quad \text{for all} \quad g \in L^2(\mathbb{T}), \quad \text{for almost every} \quad t \in [0, T], \] (51)
where $G$ is the (unique up to a set of Lebesgue measure 0) function on the torus such that $\int_{\mathbb{T}} G \, d\theta = 0$ and $G' = g$.

As in Corollary 2.3, consider a sequence $\{M_\ell, N_\ell\}_{\ell=1}^\infty$ such that
\[ M_\ell \uparrow \infty; \quad N_\ell \uparrow \infty; \quad \frac{N_\ell}{M_\ell} \uparrow \infty. \]

Let $\tilde{\eta}_0^\ell$ be a step-function approximation of $\zeta_0$, such that
\[ ||\tilde{\eta}_0^\ell - \zeta_0||_{L^2} \to 0. \] (52)
Consider $\eta^\ell$ the solutions to
\[ \frac{d \eta^\ell}{dt} = -(\tilde{A} + J) \nabla \bar{Y}(\eta^\ell), \quad \eta^\ell(0) = \eta_0^\ell. \]

To obtain Theorem 2.6 from Corollary 2.3, we shall need to study the convergence of the sequence $\eta^\ell$. It is given by the following result.

Proposition 4.2. With the notations above, the sequence of step functions $\tilde{\eta}^\ell$ converges strongly in $L^\infty_t(H^{-1}_\theta)$ to the unique weak solution of (18) with initial condition $\zeta_0$.

The key estimate which will allow us to pass to the limit is the fact that, when $N$ goes to infinity, the Euclidean product associated to $A^{-1}$ behaves like the $H^{-1}$ norm. This is the content of the following lemma :

Lemma 4.3. There exists $C < +\infty$ such that, for any $x \in X$, if $\bar{x}$ is the associated step function (defined by (17)), then
\[ \frac{1}{C^2} ||\bar{x}||^2_{H^{-1}} \leq \frac{1}{N} \langle A^{-1} x, x \rangle \leq C ||\bar{x}||^2_{H^{-1}}. \]

Moreover, if $\bar{x}$ is bounded in $L^2$, then
\[ \left| ||\bar{x}||^2_{H^{-1}} - \frac{1}{N} \langle A^{-1} x, x \rangle \right| \leq \frac{C}{N}. \]

These estimates have been proven in section 6.3 of [2].

We delay the proof of Proposition 4.2, and first prove Theorem 2.6.

Proof of Theorem 2.6. Our aim is to apply Corollary 2.3. To do this, we need to check that assumptions (i) to (x) hold with uniform constants. Assumptions (i) to (vii) have been checked in [2], and assumption (viii) in [1]. Assumption (x) can be immediately checked by the direct
computation of $JA$ and $AJ$. Finally, it is easy to see that for any $x \in X$, we have

$$\langle -J^2 x, x \rangle = |Jx|^2$$

$$= \frac{N^2}{4} \sum_{i=1}^{N} (x_{i+1} - x_{i-1})^2$$

$$\leq \frac{N^2}{4} \sum_{i=1}^{N} 2(x_{i+1} - x_i)^2 + 2(x_i - x_{i-1})^2$$

$$= N^2 \sum_{i=1}^{N} (x_{i+1} - x_i)^2$$

$$= \langle A x, x \rangle,$$  \hspace{1cm} (53)

and therefore assumption (ix) holds with $c = 1$.

Applying Corollary 2.3, we get

$$\lim_{\ell \uparrow \infty} \sup_{0 \leq t \leq T} \int \langle (x - NP^s \eta(t)), A^{-1} (x - NP^s \eta(t)) \rangle f(t, x) \mu(dx) = 0.$$  \hspace{1cm} (54)

By Lemma 4.3, this implies

$$\lim_{\ell \uparrow \infty} \sup_{0 \leq t \leq T} \int \|\dot{x} - \dot{\eta}(t)\|_{H^{-1}}^2 f(t, x) \mu(dx) = 0.$$  \hspace{1cm} (55)

Applying Proposition 4.2 and using the triangle inequality then concludes the proof.

We now turn to the proof of Proposition 4.2. It is based on the following six lemmas, and closely follows the method of [2], with additional arguments to take into account the extra first-order term that appear due to the addition of $J$ to the dynamics.

**Lemma 4.4.** Assume $\bar{H}$ is convex. Then $\eta$ satisfies (5) with initial condition $\eta(0) = \eta_0$ if and only if

$$2 \int_0^T \bar{H}(\eta) \beta(t) dt \leq \int_0^T \left[ \bar{H}(\eta + g) + \bar{H}(\eta - PA^{-1}NP^t g) \right] \beta(t) dt - \int_0^T \langle g, (\bar{A})^{-1} \eta \rangle_{Y} \dot{\beta}(t) dt, \hspace{1cm} (54)$$

for all $g \in Y$ and smooth $\beta : [0, T] \rightarrow [0, \infty)$.

Similarly, assume that $\varphi$ is convex. Then $\zeta$ satisfies (51) if and only if

$$2 \int_0^T \int_{\mathbb{T}^1} \varphi(\zeta(t, \theta)) \beta(t) d\theta dt$$

$$\leq \int_0^T \int_{\mathbb{T}^1} \left[ \varphi(\zeta(t, \theta) + g(\theta)) + \varphi(\zeta(t, \theta) - G(\theta)) \right] \beta(t) d\theta dt - \int_0^T \langle g(\cdot), \zeta(t, \cdot) \rangle_{H^{-1}} \dot{\beta}(t) dt, \hspace{1cm} (55)$$

for all $g \in L^2_{\mathbb{T}^1}$ and smooth $\beta : [0, T] \rightarrow [0, \infty)$, where $G$ is the (unique up to a set of Lebesgue measure 0) function on the torus such that $\int_{\mathbb{T}^1} G d\theta = 0$ and $G' = g$.

**Proof.** The proof of this Lemma is modified from that of Lemma 36 in [2]. We show that (5) is equivalent to (54). The equivalence of (51) and (55) follows analogously.

The weak form of (5) is given by

$$\int_0^T \langle g, (\bar{A})^{-1} \eta \rangle_{Y} \dot{\beta}(t) dt = \int_0^T \left[ \langle g, \nabla_{Y} \bar{H}(\eta) \rangle_{Y} - \langle PA^{-1}NP^t g, \nabla_{Y} \bar{H}(\eta) \rangle_{Y} \right] \beta(t) dt, \hspace{1cm} (56)$$
for all \( g \in Y \) and smooth \( \beta: [0, T] \to [0, \infty) \). We now show that (56) implies (54). Since \( \bar{H} \) is convex, we have

\[
\langle g - PA^{-1}NJP^tg, \nabla_Y \bar{H}(\eta) \rangle_Y \leq \langle \bar{H}(\eta + g) - \bar{H}(\eta) \rangle + \langle \bar{H}(\eta - PA^{-1}NJP^tg) - \bar{H}(\eta) \rangle
\]

\[
= -2\bar{H}(\eta) + \bar{H}(\eta + g) + \bar{H}(\eta - PA^{-1}NJP^tg).
\]

(57)

Substituting (57) into (56), we obtain (54)

\[
\int_0^T \langle g, (\bar{A})^{-1}\eta \rangle_Y \beta(t) dt \\
\leq -2 \int_0^T \bar{H}(\eta) \beta(t) dt + \int_0^T \left[ \bar{H}(\eta + g) + \bar{H}(\eta - PA^{-1}NJP^tg) \right] \beta(t) dt.
\]

(58)

Next we show (54) implies (56). Take \( \bar{g} = \varepsilon g \) in (54), for some \( \varepsilon > 0 \) and \( g \in Y \), we get

\[
\int_0^T \langle g, (\bar{A})^{-1}\eta \rangle_Y \beta(t) dt \leq \int_0^T \left[ \bar{H}(\eta + \varepsilon g) - \bar{H}(\eta) \right] \beta(t) dt.
\]

By passing to the limit \( \varepsilon \to 0 \), we get

\[
\int_0^T \langle g, (\bar{A})^{-1}\eta \rangle_Y \beta(t) dt \leq \int_0^T \langle g - PA^{-1}NJP^tg, \nabla_Y \bar{H}(\eta) \rangle_Y \beta(t) dt.
\]

Similarly now by taking \( \tilde{g} = -\varepsilon g \), we obtain the opposite inequality

\[
\int_0^T \langle g, (\bar{A})^{-1}\eta \rangle_Y \beta(t) dt \geq \int_0^T \langle g - PA^{-1}NJP^tg, \nabla_Y \bar{H}(\eta) \rangle_Y \beta(t) dt.
\]

Thus (56) is proven. \( \square \)

**Lemma 4.5.** Let \( \{\eta^t\}_{t=1}^\infty \) be a sequence of solutions of (5) with initial data \( \eta_0^t \) satisfying \( \|\eta_0^t\|_{L^2} \leq C \). There exists a constant \( C \) independent of \( t \) such that

\[
\int_0^T \left\langle \frac{d\eta^t}{dt}(t), (\bar{A})^{-1}\frac{d\eta^t}{dt}(t) \right\rangle dt \leq C
\]

(59)

\[
\sup_{t\in[0,T]} \langle \eta^t(t), \eta^t(t) \rangle_Y \leq C.
\]

(60)

As a consequence, there is a subsequence of the sequence of the associated step functions \( \bar{\eta}^t \) and a function \( \eta_* \) such that

\( \bar{\eta}^t \rightharpoonup \eta_* \) weak-* in \( L^\infty(L^2) = (L^1(L^2))^* \).

**Proof.** According to proof of (34), we have

\[
\bar{H}(\eta^t(t)) \leq e^{C(T+1)} \bar{H}(\eta_0^t) \quad \text{for all} \quad t \in [0, T].
\]

(61)

Since \( \bar{H} \) is uniformly convex, we obtain

\[
\langle \eta^t(t), \eta^t(t) \rangle_Y \leq C(\bar{H}(\eta^t(t)) + 1) \leq Ce^{CT} (\bar{H}(\eta_0^t) + 1) \leq C,
\]

which is (60). Now we establish (59). From (5), we have

\[
\langle \eta^t(t), (\bar{A})^{-1}\eta^t(t) \rangle = \langle \bar{A}(I + PJA^{-1}NP^t)\nabla_Y \bar{H}(\eta^t(t)), (I + PJA^{-1}NP^t)\nabla_Y \bar{H}(\eta^t(t)) \rangle
\]

\[
\leq 2\langle \bar{A}\nabla_Y \bar{H}(\eta^t(t)), \nabla_Y \bar{H}(\eta^t(t)) \rangle + \langle PJA^{-1}NP^t\nabla_Y \bar{H}(\eta^t(t)), PJA^{-1}NP^t\nabla_Y \bar{H}(\eta^t(t)) \rangle
\]

\[
\leq 2\langle \bar{A}\nabla_Y \bar{H}(\eta^t(t)), \nabla_Y \bar{H}(\eta^t(t)) \rangle + C(\bar{H}(\eta^t(t)) + 1)
\]

(30)

\[
\leq 2\langle \bar{A}\nabla_Y \bar{H}(\eta^t(t)), \nabla_Y \bar{H}(\eta^t(t)) \rangle + C(\bar{H}(\eta^t(t)) + 1)
\]

(31)
Therefore,
\[
\int_0^T \langle \dot{q}^f(t), (A)^{-1}\dot{q}^f(t) \rangle \, dt \leq 2 \int_0^T \left( \langle A\nabla YH(\eta^f(t)), \nabla YH(\eta^f(t)) \rangle + C(H(\eta^f(t)) + 1) \right) \, dt
\]

\[(34),(61) \leq C,
\]

which is (59).

\[\square\]

**Lemma 4.6.** Let \(\{\eta^f\}_1^\infty\) be a sequence of solutions of (5) satisfying Lemma 4.5. We take any subsequence such that the associated step functions weak-* converge in \((L^1(L^2))^\ast\) to a limit \(\eta_*\). Then on any bounded time interval, we have

\[\eta_* \in L^\infty(L^2), \quad \frac{\partial \eta_*}{\partial t} \in L^2(H^{-1}), \quad \varphi'(\eta_*) \in L^2(L^2).\]  

(62)

**Proof.** Having the estimate in Lemma 4.5, the proof of this Lemma is the same as that of Lemma 35 in [2]; hence we omit it here.

\[\square\]

**Lemma 4.7.** If \(\bar{g}^f \rightarrow \bar{g}\) strongly in \(H^{-1}(\mathbb{T})\) and sup \(\|g^f\|_{L^2} < \infty\) then \(-PA^{-1}JNP^f g^f \rightarrow G\) strongly in \(L^2(\mathbb{T})\) where \(G\) is the primitive of \(\bar{g}\).

\(PA^{-1}JNP^f g^f\) is the step function associated to \(PA^{-1}JNP^f g^f\), as in (17). We only formally gave the definition for elements of \(X_{N,0}\), while \(PA^{-1}JNP^f g^f\) is in \(Y_{M,0}\), but since \(Y_{M,0} \sim X_{M,0}\), this is not an issue, and we just use the same definition, with mesh size \(M^{-1}\) instead of \(N^{-1}\).

**Proof.** Set

\[D = N \begin{pmatrix} 1 & -1 \\ -1 & 1 \\ & \ddots & \ddots \\ & & 1 & -1 \\ -1 & 1 \\ 1 & -1 \end{pmatrix},\]

(63)

then we can write

\[A = DD^T, \quad J = \frac{1}{2}(D^T - D).\]

Hence

\[JA^{-1} = \frac{1}{2}(D^T - D)(D^T D)^{-1} = \frac{1}{2}(D^T - D)D^{-1}(D^T)^{-1} = \frac{1}{2}(D^{-1} - (D^T)^{-1}).\]

(64)

The inverse of \(D\) and \(D^T\) can be computed explicitly

\[D^{-1} = \frac{1}{2N} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & -1 \\ 1 & -1 & 1 \end{pmatrix}, \quad (D^T)^{-1} = (D^{-1})^T.\]

So we obtain

\[D^{-1} - (D^T)^{-1} = \frac{1}{N} \begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ -1 & 0 & 0 \end{pmatrix},\]

(65)
Let \( \xi = \begin{pmatrix} \xi_1 \\ \vdots \\ \xi_M \end{pmatrix} \in Y = \mathbb{R}^M \) be given. We now compute \( P A^{-1} J N P^t \xi \) explicitly.

By definition of \( P^t \), we have

\[
NP^t \xi = \begin{pmatrix} \xi_1 \\ \vdots \\ \xi_1 \\ \xi_2 \\ \vdots \\ \xi_M \\ \vdots \\ \xi_M \end{pmatrix} \in \mathbb{R}^N = \mathbb{R}^{KM}.
\] (66)

From (64), (65) and (66), we have

\[
A^{-1} J N P^t \xi = \frac{1}{2N} \begin{pmatrix} K(\xi_1 + \cdots + \xi_M) \\ (K - 1)\xi_1 + K(\xi_2 + \cdots + \xi_M) \\ \vdots \\ (K - 1)\xi_2 + K(\xi_3 + \cdots + \xi_M) \\ K(\xi_3 + \cdots + \xi_M) \\ \vdots \\ K(\xi_1 + \cdots + \xi_M) \end{pmatrix} - \frac{1}{2N} \begin{pmatrix} \xi_1 \\ 2\xi_1 \\ \vdots \\ K\xi_1 + \xi_2 \\ \vdots \\ K(\xi_1 + \cdots + \xi_M) \end{pmatrix}.
\]

Therefore, by definition of \( P \),

\[
P A^{-1} J N P^t \xi = \frac{1}{2M} \begin{pmatrix} \xi_1 + \xi_2 + \cdots + \xi_M \\ \xi_2 + \cdots + \xi_M \\ \vdots \\ \xi_M \end{pmatrix} - \frac{1}{2M} \begin{pmatrix} \xi_1 + \xi_2 \\ \vdots \\ \xi_1 + \xi_2 + \cdots + \xi_M \end{pmatrix}.
\]

Recall that the \( \xi_i \) sum up to 0, and hence we can re-write the above equality as

\[
- P A^{-1} J N P^t \xi = \frac{1}{2M} \begin{pmatrix} \xi_1 \\ \xi_1 + \xi_2 \\ \vdots \\ \xi_1 + \xi_2 + \cdots + \xi_M \end{pmatrix} + \frac{1}{2M} \begin{pmatrix} 0 \\ \xi_1 \\ \vdots \\ \xi_1 + \xi_2 + \cdots + \xi_{M-1} \end{pmatrix}
\]

\[
= \frac{1}{M} \begin{pmatrix} \xi_1 \\ \xi_1 + \xi_2 \\ \vdots \\ \xi_1 + \xi_2 + \cdots + \xi_M \end{pmatrix} - \frac{1}{2M} \begin{pmatrix} \xi_1 \\ \xi_2 \\ \vdots \\ \xi_M \end{pmatrix}.
\]

It follows that

\[
- P A^{-1} J N P^t \xi = \Upsilon_\xi - \frac{1}{2M} \xi.
\]
where $\Upsilon_\xi$ denotes the primitive of $\xi$. By the assumption $\overline{g^T} \to \overline{g}$ strongly in $H^{-1}$ and by definition of $H^{-1}$-norm, we have

$$\Upsilon_{g^T} = -PA^{-1}JNP^t g^T + \frac{1}{2M} \overline{g^T} \to \Upsilon_g \equiv G \text{ strongly in } L^2(\mathbb{T}).$$

The assertion then follows because

$$\| -PA^{-1}JNP^t g^T - G \|_{L^2} \leq \| -PA^{-1}JNP^t g^T + \frac{1}{2M} \overline{g^T} - G \|_{L^2} + \frac{1}{2M} \| \overline{g^T} \|_{L^2} \to 0.$$ 

\[\square\]

**Lemma 4.8.** Suppose that the sequence $\eta^f$ satisfies (59), (60) and (54), and consider a subsequence such that

$$\overline{\eta^f} \to \eta_* \text{ weak-* in } L^\infty(L^2) = (L^1(L^2))^*.$$ 

holds. Let $\xi^t = \pi_\xi(\xi_0 + \overline{\eta}^f) - \eta^f$, where $\xi$ is an arbitrary $L^2$ function and $\pi_\xi$ is the $L^2$-projection onto elements of $Y$. Let $\Xi$ be the primitive with average 0 of $\xi$. Then we have

(i)\[
\liminf_{\ell} \int_0^T H(\eta^f(t)) \beta(t) dt \geq \int_0^T \int_\mathbb{T} \varphi(\eta_*(t, \theta)) \beta(t) d\theta dt;
\]

(ii)\[
\lim_{\ell} \int_0^T H(\eta^f(t) + \xi^t(t)) \beta(t) dt = \int_0^T \int_\mathbb{T} \varphi(\eta_*(t, \theta) + \xi(t, \theta)) \beta(t) d\theta dt;
\]

(iii)\[
\lim_{\ell} \int_0^T H(\eta^f(t) - PA^{-1}JNP^t \xi^t(t)) \beta(t) dt = \int_0^T \int_\mathbb{T} \varphi(\eta_*(t, \theta) - \Xi(\theta)) \beta(t) d\theta dt;
\]

(iv)\[
\lim_{\ell} \int_0^T (\xi^t(t), A^{-1} \eta^f(t))_Y \hat{\beta}(t) dt = \int_0^T (\xi(\theta), \eta_*(t, \theta))_{H^{-1}} \hat{\beta}(t) dt.
\]

**Proof.** (i), (ii) and (iv) have already been proven in Lemma 37 of [2], so we only have to prove (iii).

Recall that $H(y) = M^{-1} \sum \psi_K(y_k) + N^{-1} \log Z$, where $\psi_K$ was defined in (15). Since $\overline{\eta}^f$ converges to $\eta_*$ and $PA^{-1}JNP^t \xi^t(t)$ converges to $\Xi$, by weak lower-semi continuity and the uniform convergence of $\psi_K$ to $\varphi$ (see Proposition 31 in [2]) we immediately get

$$\liminf_{\ell} \int_0^T H(\eta^f(t) - PA^{-1}JNP^t \xi^t(t)) \beta(t) dt \geq \int_0^T \int_\mathbb{T} \varphi(\eta_*(t, \theta) - \Xi(\theta)) \beta(t) d\theta dt$$

so we only need to prove the associated upper bound. Let $g^f(t)$ be a sequence of elements of $Y$ such that $\overline{g^f}$ strongly converges in $L^\infty(L^2)$ to $\eta_* - \Xi$. Since we then have

$$\int_0^T H(\overline{g^f(t)}) \beta(t) dt \to \int_0^T \int_\mathbb{T} \varphi(\eta_*(t, \theta) - \Xi(\theta)) \beta(t) d\theta dt$$

we only need to show that

$$\limsup_{\ell} \int_0^T H(\eta^f(t) - PA^{-1}JNP^t \xi^t(t)) \beta(t) dt - \int_0^T H(\overline{g^f(t)}) \beta(t) dt \leq 0.$$ 

Let $A_M$ be the discrete Laplacian with scaling factor $M^2$ on $Y$. Since $\psi_K$ is convex, we have
\[ H(\eta^\ell(t) - PA^{-1}JNP^\ell \xi^\ell(t)) - H(\eta'(t)) = \frac{1}{M} \sum_{i=1}^{M} \psi_K(\eta_i^\ell - (PA^{-1}JNP^\ell \xi_i^\ell), (\eta_i' - (PA^{-1}JNP^\ell \xi_i')) \big) \]

\[ \leq \frac{1}{M} \sum_{i=1}^{M} \psi_K(\eta_i^\ell - (PA^{-1}JNP^\ell \xi_i^\ell), (\eta_i' - (PA^{-1}JNP^\ell \xi_i')) \big) \]

\[ = (\nabla \hat{H}(\eta^\ell - PA^{-1}JNP^\ell \xi^\ell), (\eta^\ell - PA^{-1}JNP^\ell \xi^\ell - \eta'))_Y \]

\[ \leq (A_M \nabla \hat{H}(\eta^\ell - PA^{-1}JNP^\ell \xi^\ell), \nabla \hat{H}(\eta^\ell - PA^{-1}JNP^\ell \xi^\ell))^{1/2}_Y \]

\[ \times (A_M^{-1}(\eta^\ell - PA^{-1}JNP^\ell \xi^\ell - \eta'), (\eta^\ell - PA^{-1}JNP^\ell \xi^\ell - \eta'))^{1/2}_Y \]

Since \( (A_M^{-1}, \cdot)_Y \) behaves like the squared \( H^{-1} \) norm, the fact that \( \eta^\ell - PA^{-1}JNP^\ell \xi^\ell \) and \( g^\ell \) converge to the same limit in \( L^\infty(H^{-1}) \) implies that

\[ (A_M^{-1}(\eta^\ell - PA^{-1}JNP^\ell \xi^\ell - \eta'), (\eta^\ell - PA^{-1}JNP^\ell \xi^\ell - \eta'))_Y \rightarrow 0, \]

and therefore it will be enough to show that

\[ \int_0^T (A_M \nabla \hat{H}(\eta^\ell - PA^{-1}JNP^\ell \xi^\ell), \nabla \hat{H}(\eta^\ell - PA^{-1}JNP^\ell \xi^\ell))_Y dt < C. \]

Since under our assumptions \( \psi_K \) is bi-Lipschitz, we have

\[ (A_M \nabla \hat{H}(\eta^\ell - PA^{-1}JNP^\ell \xi^\ell), \nabla \hat{H}(\eta^\ell - PA^{-1}JNP^\ell \xi^\ell))_Y \]

\[ = M \sum_{i=1}^{M} (\psi_K(\eta_i^\ell - (PA^{-1}JNP^\ell \xi_i^\ell), (\eta_i' - (PA^{-1}JNP^\ell \xi_i'))) \big)^2 \]

\[ \leq CM \sum_{i=1}^{M} (\eta_i^\ell - (PA^{-1}JNP^\ell \xi_i^\ell))^2 + ((PA^{-1}JNP^\ell \xi_i^\ell), (PA^{-1}JNP^\ell \xi_i'))^2 \]

\[ \leq CM \sum_{i=1}^{M} (\psi_K(\eta_i^\ell), (\eta_i'))^2 + \frac{C}{M} \sum_{i=1}^{M} (\xi_i^\ell - \xi_i')^2 \]

\[ \leq C(0, \nabla \hat{H}(\eta^\ell), \nabla \hat{H}(\eta^\ell)) + C||\xi^\ell||^2_{L^2}. \]

Since \( \xi^\ell \) converges in \( L^2, ||\xi^\ell||^2_{L^2} \) is bounded. To conclude, we then only require (59) and the fact that

\[ (A_M y, y) \leq C(\tilde{A} y, y) \quad \forall y \in Y. \] (67)

This statement is equivalent to bounding from below \( A_M^{-1} \) by \( \tilde{A}^{-1} \). This does hold, since we have

\[ (\tilde{A}^{-1} y, y)_Y = \frac{1}{N} (A^{-1}NP^\ell y, NP^\ell y)_X \]

\[ \leq C||NP^\ell y||_{H^{-1}} \]

\[ \leq C||y||^2_{H^{-1}} \]

\[ \leq C(A_M^{-1} y, y)_Y \]

which concludes the proof.

Finally, we need to prove uniqueness of solutions to the limiting PDE:
Lemma 4.9. Given an initial condition \( \zeta_0 \), there is at most one solution to (18).

Proof. Let \( \zeta_1 \) and \( \zeta_2 \) be two solutions of (18) with same initial condition. Let \( g_1 \) and \( g_2 \) be mean-zero primitives (in space) of \( \zeta_1 \) and \( \zeta_2 \). Then, for any \( \lambda > 0 \),

\[
F'(t) = -\int_T (\varphi'(\zeta_1) - \varphi'(\zeta_2))(\zeta_1 - \zeta_2)d\theta + \int_T (\varphi'(\zeta_1) - \varphi'(\zeta_2))(g_1 - g_2)d\theta
\leq -\inf_{\varphi''} \frac{1}{2} \int_T (\zeta_1 - \zeta_2)^2 d\theta + \frac{\lambda}{2} \int_T (\varphi'(\zeta_1) - \varphi'(\zeta_2))^2 d\theta + \lambda \int_T (g_1 - g_2)^2 d\theta
\leq -\inf_{\varphi''} \frac{1}{2} \int_T (\zeta_1 - \zeta_2)^2 d\theta + \frac{\sup_{\varphi''} \lambda}{2} \int_T (\zeta_1 - \zeta_2)^2 d\theta + \frac{1}{\lambda} F(t)
\]

Taking \( \lambda = \inf_{\varphi''} \frac{\sup_{\varphi''}}{2} \), we obtain a differential inequality which, by Gronwall’s lemma, implies that \( \zeta_1 = \zeta_2 \).

We can now prove Proposition 4.2:

Proof of Proposition 4.2. According to Lemma 4.5, we can consider a subsequence such that

\( \bar{\eta}_\ell \rightharpoonup \eta^* \) weak-\(^*\) in \( L^\infty(L^2) = (L^1(L^2))^* \).

and strongly in \( L^\infty(H^{-1}) \). By Lemma 4.6, \( \eta^* \) satisfies (50). According to Lemma 4.4, \( \eta^\ell \) satisfies (54). Passing to the limit using Lemma 4.8, we see that \( \eta^* \) satisfies (55), and therefore is a weak solution of (18).

Since Lemma 4.9 guarantees uniqueness of the weak solution, the full sequence \( (\eta^\ell) \) converges to the unique weak solution of (18).

References


