

Unsplittable Euclidean Capacitated Vehicle Routing

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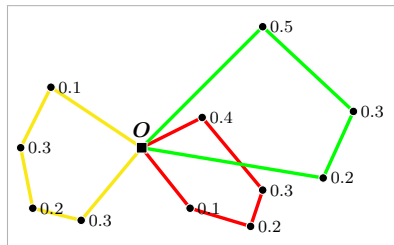
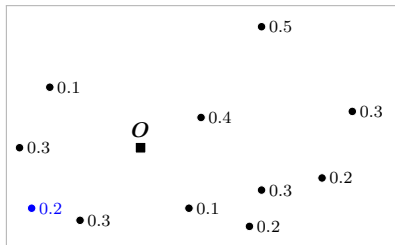
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Capacitated vehicle routing problem (CVRP)

Input:

- depot O
- n terminals with **unsplittable** demands in $(0, 1]$

Minimize total length of tours s.t. each tour has total demand ≤ 1



Fundamental problem in operations research

Equal demands



Unequal demands



- general metrics
- Euclidean plane
- planar graphs
- trees
- graphs of bounded treewidth
- graphs of bounded highway dimension
- graphic metrics

Previous and new results on the Euclidean CVRP

Arbitrary demands

- **1.5-hard** [folklore]
- **2.694-approximation** [Friggstad et al. 2022]
- **$(2 + \epsilon)$ -approximation for any $\epsilon > 0$ [our result]**

Big demands only

- **NP-hard** [folklore]
- **2.694-approximation** [Friggstad et al. 2022]
- **$(1 + \epsilon)$ -approximation for any $\epsilon > 0$ [our result]**

Note: Both our results **match the best known approximation factors** in the corresponding equal demand settings.

Big demands only

Our result

$(1 + \epsilon)$ -approximation for any $\epsilon > 0$

Polynomial time algorithm under assumptions

Definition

Let $\epsilon > 0$. A demand is **big** if it is at least ϵ , and is **small** otherwise.

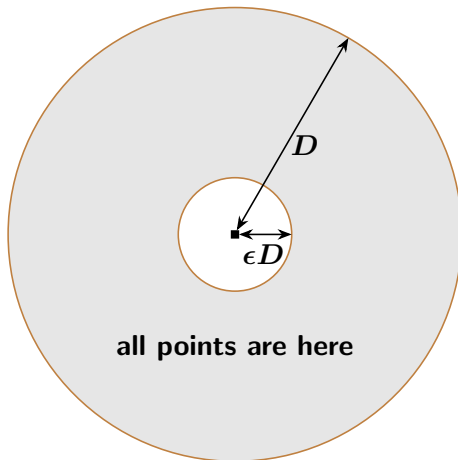
Polynomial time exact algorithm for big demands only, assuming:

- 1 $O_\epsilon(1)$ **locations**
- 2 $O_\epsilon(1)$ **distinct demands** at each location

Q: How to achieve both assumptions?

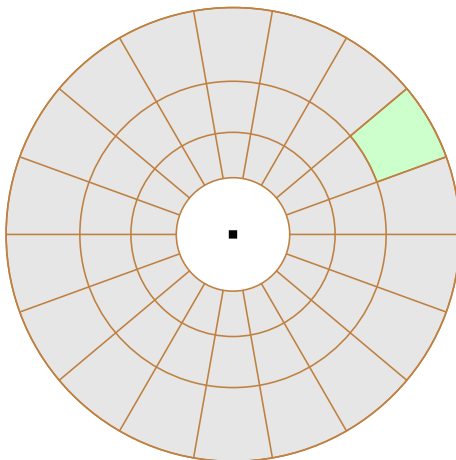
Reducing the number of locations (1/3)

Step 1: Reduce to **bounded distance**



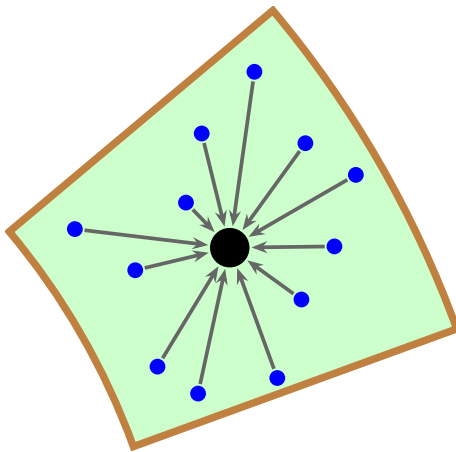
Reducing the number of locations (2/3)

Step 2: Decompose the gray area into $O_\epsilon(1)$ cells



Reducing the number of locations (3/3)

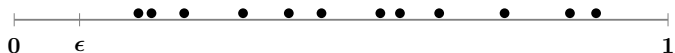
Step 3: Move **each terminal to the center of its cell**



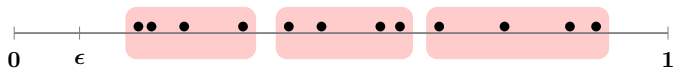
Reducing the number of distinct demands

Adaptive rounding

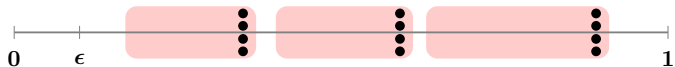
(a) Sort all demands at a center



(b) Make groups of equal cardinality

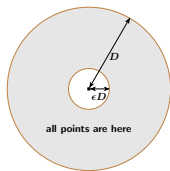


(c) Round up to maximum demand in group

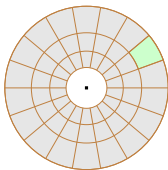


Algorithm for big demands only

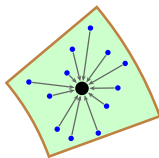
- 1 Reduce to **bounded distance**
- 2 Decompose into **cells**
- 3 Move each big terminal to the **center** of its cell
- 4 Apply **adaptive rounding** on the demands at each center
- 5 Solve the resulting instance in **polynomial time**



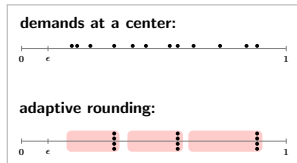
1



2



3



4

Arbitrary demands

Our result

$(2 + \epsilon)$ -approximation for any $\epsilon > 0$

Case 1: Optimal solution has sufficiently many tours (1/5)

Algorithm for big demands only (revisited)

- 1 Reduce to **bounded distance**
- 2 Decompose into **cells**
- 3 Move each big terminal to the **center** of its cell
- 4 Apply **adaptive rounding** on the demands at each center
- 5 Solve the resulting instance in **polynomial time**

Q: How to deal with small demands?

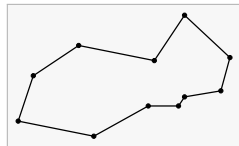
A: Insert one step between 2 and 3 :

Cluster the small terminals in each cell into big terminals

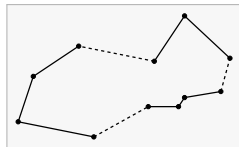
Case 1: Optimal solution has sufficiently many tours (2/5)

Cluster the small terminals in each cell into big terminals:

- (a) Compute a TSP tour on the small terminals **in the cell**



- (b) Partition the tour into segments, each of total demand $\approx \epsilon$



- (c) For each segment, connect its endpoints to the center of the cell



a big terminal at the center of the cell

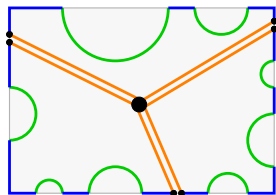


Case 1: Optimal solution has sufficiently many tours (3/5)

opt : cost of an optimal solution to the initial instance

Lemma 1

The cost within cells is at most $(1 + 2\epsilon) \cdot \text{opt}$.



- **green** is the optimal solution
- **blue** $\leq 1.5 \cdot \text{cell boundaries} \leq \epsilon \cdot \text{opt}$,
by Karp and since the optimal solution has many tours
- **orange** $\leq \epsilon \cdot \text{opt}$, since each segment has total demand $\approx \epsilon$

Case 1: Optimal solution has sufficiently many tours (4/5)

opt : cost of an optimal solution to the initial instance

opt' : cost of an optimal solution to the clustered instance

Lemma 2

The cost between cells is at most $(1 + \epsilon) \cdot \text{opt}' \leq (1 + 4\epsilon) \cdot \text{opt}$.

Construction of a near-optimal solution to the clustered instance:

- Compute a set of tours each of **capacity** $1 + \epsilon$ [Becker and Paul]
cost $\leq (1 + \epsilon) \cdot \text{opt}$
- Remove one **cluster** (of demand ϵ) from each tour
- Connect the removed clusters by a **TSP tour**
cost $\leq \epsilon \cdot \text{opt}$, since the optimal solution has many tours
- **Iterated tour partitioning** on the TSP tour
cost $\leq \epsilon \cdot \text{opt}$, since only ϵ demand is removed from each tour

Case 1: Optimal solution has sufficiently many tours (5/5)

opt : cost of an optimal solution to the initial instance

opt' : cost of an optimal solution to the clustered instance

Lemma 1

The cost within cells is at most $(1 + 2\epsilon) \cdot \text{opt}$.

Lemma 2

The cost between cells is at most $(1 + 4\epsilon) \cdot \text{opt}$.

Conclusion: Overall cost is at most $(2 + 6\epsilon) \cdot \text{opt}$.

Case 2: Optimal solution has a bounded number of tours

Algorithm

- 1 **Round down** each demand to **an integer multiple of $\frac{1}{2n}$**
- 2 Compute a $(1 + \epsilon)$ -approximation to the rounded instance [Arora]
- 3 **Split each tour into two tours**, each within the capacity

Cost analysis:

- 2 : at most $(1 + \epsilon) \cdot \text{opt}$
- 3 : doubling the cost

Conclusion: Overall cost is at most $(2 + 2\epsilon) \cdot \text{opt}$.

Summary on the Euclidean CVRP

Arbitrary demands

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Thank you!