# Probabilistic Analysis of Euclidean Capacitated Vehicle Routing

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Input:

- a depot O and n customers
- tour capacity k



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A fundamental problem in operations research, e.g., more than 3700 articles on vehicle routing at DBLP.

The ITP algorithm [Haimovich and Rinnooy Kan 1985]

compute a traveling salesman tour



**2** partition the tour into segments of at most k customers each



Source the endpoints of each segment to the depot



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Tight instance:



Tight instances seem contrived.

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Tight instance:



Q: How do we explain the popularity of ITP?

A: Perhaps ITP works particularly well on non-contrived instances.

Approximation ratio: upper bound = lower bound =  $2 - \frac{1}{k}$ [Altinkemer and Gavish 1990, Li and Simchi-Levi 1990]

Tight instance:



Q: How well does it work on random instances?

Random Setting: Customers are *independent*, *identically distributed* (*i.i.d.*) random points in the unit square.



### Haimovich and Rinnooy Kan 1985

- for  $k = o(\sqrt{n})$ : 1 + o(1)
- for  $k = \omega(\sqrt{n})$ : 1 + o(1)
- for  $k = \Theta(\sqrt{n})$ : also effective?

### Upper bound on the approximation ratio of ITP in the random setting

- 1.995 [Bompadre, Dror, and Orlin 2007]
- 1.915 [this work]

#### Lower bound on the approximation ratio of ITP in the random setting

•  $1 + c_0$  for some constant  $c_0 > 0$  [this work]

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# High-Level Analysis

Two factors in the cost of an ITP solution [Haimovich and Rinnooy Kan 1985]:

- $\blacksquare$  traveling salesman tour cost:  $\mathrm{TSP}$
- **2** radius cost: radius  $= \frac{2}{k} \cdot \sum_{x} \delta(O, x)$



#### Properties:

- $ITP \le radius + TSP$
- $OPT \ge radius$
- $OPT \ge TSP$

Implication:

• ITP is a 2-approximation.

Properties:

- $ITP \leq radius + TSP$
- $OPT \ge radius + 0.085 \cdot TSP$
- $OPT \ge TSP$

### Implication:

• ITP is a 1.915-approximation.

# Proof for the Lower Bound on OPT(1/4)

Consider a tour T visiting m points.

$$L := \frac{1}{m} \sum_{x \in T} \delta(O, x) \quad \text{and} \quad \Delta := \max_{x \in T} \delta(O, x) - L.$$

 $\cot(T) \ge 2(L + \Delta)$ 

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$$W = \left\{ x \in T \mid \delta(O, x) \ge \text{threshold} \right\}$$
  

$$\operatorname{cost}(T) \ge 2 \cdot \text{threshold} + \operatorname{TSP}(W)$$
  
Facts:  

$$|W| \ge \lambda \cdot m$$
  

$$\operatorname{TSP}(W) \ge \sum_{x \in W} \delta(x, W \setminus \{x\})$$

 $----L+\Delta$ 

 $\cap$ 

# Proof for the Lower Bound on OPT(2/4)

Summing over all tours T in an optimal solution, we obtain

$$\begin{aligned} \text{OPT} &\geq \sum_{T} 2(L_T + \Delta_T) \\ \text{OPT} &\geq \sum_{T} 2\left(L_T - \frac{\lambda}{1 - \lambda} \cdot \Delta_T\right) + \sum_{x \in U} \delta(x, U \setminus \{x\}), \text{ where } U = \bigcup_{T} W_T. \end{aligned}$$

Linear combination of both inequalities with coefficients  $\lambda$  and  $1 - \lambda$ :

#### Structural Theorem

Let V be a set of n points in any metric. For any  $\lambda \in (0,1)$ , there exists a subset  $U \subseteq V$  of cardinality at least  $\lambda \cdot n$  such that

$$OPT \ge \text{radius} + (1 - \lambda) \sum_{x \in U} \delta(x, U \setminus \{x\}).$$

# Proof for the Lower Bound on OPT(3/4)

Next, we analyze

$$\min_{U} \sum_{x \in U} \delta(x, U \setminus \{x\})$$

in the probabilistic setting for a subset  $U \subseteq V$  of cardinality at least  $\lambda \cdot n$ .

Lemma

Asymptotically almost surely, 
$$\min_{U} \sum_{x \in U} \delta(x, V \setminus \{x\}) > f(\lambda) \cdot \sqrt{n}, \text{ where}$$
$$f(\lambda) := \frac{1}{2} \operatorname{erf} \left( \sqrt{\ln \frac{1}{1-\lambda}} \right) - (1-\lambda) \cdot \sqrt{\frac{1}{\pi} \cdot \ln \frac{1}{1-\lambda}} \text{ in which } \operatorname{erf}(\cdot) \text{ is the}$$
Gauss error function.

Technique: weak law of large numbers on the closest point distance [Penrose and Yukich 2003]

### Proof for the Lower Bound on OPT(4/4)

OPT  $\geq$  radius +  $(1 - \lambda) \cdot f(\lambda) \cdot \sqrt{n}$ , for any  $\lambda$ .

Let  $h(\lambda) = (1 - \lambda) \cdot f(\lambda)$ . The maximum value of  $h(\lambda)$  is 0.0786.



OPT ≥ radius + 0.0786 · √n
TSP < 0.922 · √n [Steinerberger 2015]</li>

Conclusion:  $OPT \ge radius + 0.085 \cdot TSP$ .

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# **ITP** Solution

- Partition the unit square into small squares
- Make a tour to visit points in each small square



### New Solution: Decomposition of the Unit Square



# New Solution: Decomposition of a Box



### New Solution: A Mixed Tour



- Positive effect on the TSP cost
- Negative effect on the radius cost

Delicate definition of the decomposition  $\bigcup \\ \mbox{Improvement upon an ITP solution}$ 

Cost of an ITP solution = radius + TSP Cost of the new solution < radius + TSP -  $0.000068 \cdot \sqrt{n}$ 

Conclusion: ITP is at best a  $(1 + c_0)$ -approximation for  $c_0 > 0$ .

We give a partial answer to the question:

How good is the Iterated Tour Partitioning algorithm? Our partial answer in the random setting:

Approximation ratio between  $1 + c_0$  and 1.915.

Open problems:

- Reduce the gap between  $1 + c_0$  and 1.915 for the performance of ITP in the random setting.
- 2 Design a PTAS for capacitated vehicle routing in the random setting.