# A Tight $(1.5 + \epsilon)$ -Approximation for Unsplittable Capacitated Vehicle Routing on Trees

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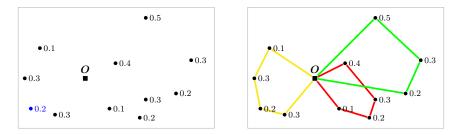
ICALP 2023

# Unsplittable capacitated vehicle routing problem (UCVRP)

Input:

- depot O
- n terminals with unsplittable demands in (0,1]

Minimize total length of tours s.t. each tour has total demand  $\leq 1$ 



Fundamental problem in operations research

### **Equal Demand**



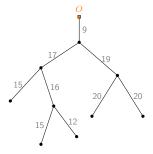
2023 Nie and Zhou

### **Unequal Demand**

1981	Golden and Wong
1987	Altinkemer and Gavish
1991	Labbé, Laporte, and Mercure
2021	<ul> <li>Blauth, Traub, and Vygen</li> </ul>
2022	Friggstad, Mousavi, Rahgoshay, and Salavatipour
2023	<ul> <li>Grandoni, Mathieu, and Zhou</li> </ul>
2023	Mathieu and Zhou

- general metrics
- Euclidean plane
- planar graphs
- trees
- graphs of bounded treewidth
- graphs of bounded highway dimension
- graphic metrics

- NP-hard to approximate to better than 1.5 [Golden Wang 1981]
- polynomial-time 2-approximation [Labbé Laporte Mercure 1991]



### Our Result

polynomial-time  $(1.5 + \epsilon)$ -approximation

#### Easier versions

unit demand: PTAS [Mathieu Zhou 2022]

splittable demand: PTAS [Mathieu Zhou 2022]

infinite capacity: poly-time [folklore: TSP on trees]

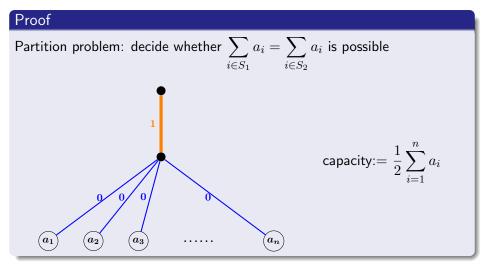
UCVRP on trees is the easiest vehicle routing problem that is APX-hard

Harder versions	
general metric:	lower bound 1.5 v.s. upper bound $3.194 + \epsilon$ [Friggstad Mousavi Rahgoshay Salavatipour 2022]
Euclidean plane:	lower bound 1.5 v.s. upper bound $2 + \epsilon$ [Grandoni Mathieu Zhou 2023]

complexity of approximation of all harder vehicle routing problems is open

### UCVRP on trees: Hardness of approximation

# NP-hard to approximate UCVRP on trees to better than 1.5 [Golden Wang 1981]



### Our Result

polynomial-time  $(1.5 + \epsilon)$ -approximation

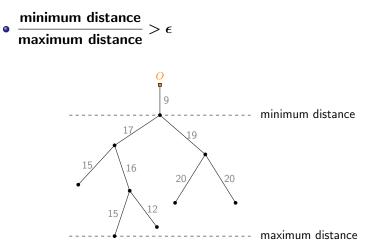
### Standard general approach

simplifying input: modifying input to have a particular structuresimplifying output: modifying output to have a particular structuredynamic programming: solving simplified problem optimally

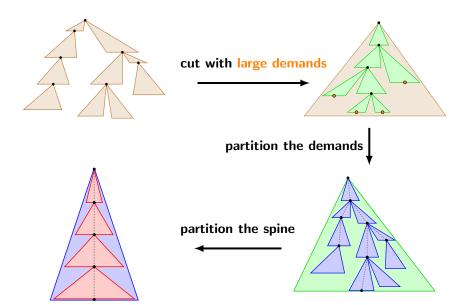
# Simplifying input

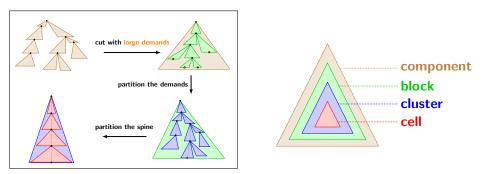
May assume without loss of generality:

- binary tree
- depot at the root, demands at the leaves



Simplifying output: Multi-level decomposition

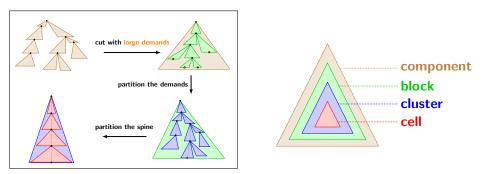




### Properties

- at most O(1) tours in component
- no large demands in block
- small total demand in cluster
- short spine in cell

Combine solutions between components by adaptive rounding and  $\ensuremath{\mathsf{DP}}$ 



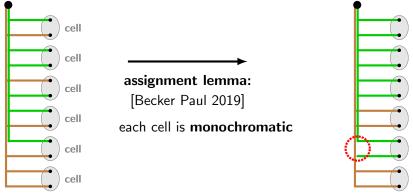
### Structure Theorem in Component

There is a **capacity-preserving** way to modify the solution, **setting aside some terminals**, so that

- in each cell, the terminals are visited by a single tour
- the terminals set aside are covered by just one additional tour
- the solution cost is increased by at most 50%

# Proof of the Structure Theorem (1/4)

For intuition: special case when all demands are small Optimal solution = green tour and brown tour

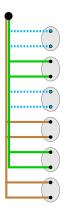


To keep green tour connected, lengthen its spine

- short spine in cell  $\implies$  lengthening is cheap
- small total demand in cluster => tour capacity increased slightly

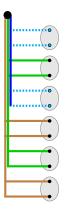
## Proof of the Structure Theorem (2/4)

Set aside demands so that each tour is within capacity



## Proof of the Structure Theorem (3/4)

Create a new tour for demands set aside by adding a piece of spine

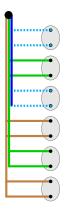


Cost increases by at most 50%:

the added spine already used by two tours: green tour and brown tour

# Proof of the Structure Theorem (4/4)

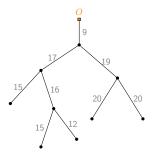
Create a new tour for demands set aside by adding a piece of spine



- Q: Why can the terminals set aside be covered by one additional tour?
- A: Play with the parameters between
  - number of tours in component (large constant), and
  - max demand of a cell or cluster (small constant)

• NP-hard to approximate to better than 1.5 [Golden Wang 1981]

• polynomial-time 2-approximation [Labbé Laporte Mercure 1991]



#### Our Result

polynomial-time  $(1.5 + \epsilon)$ -approximation

# Thank you!