

Euclidean Capacitated Vehicle Routing in the Random Setting: A 1.55-Approximation Algorithm

Zipei Nie^{1,2}

Hang Zhou³

¹Lagrange Mathematics and Computing Research Center, Huawei, France

²Institut des Hautes Études Scientifiques, France

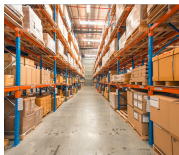
³École Polytechnique, Institut Polytechnique de Paris, France

European Symposium on Algorithms 2024

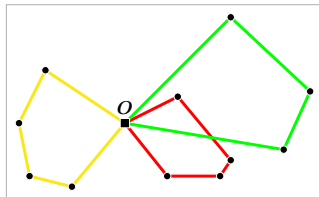
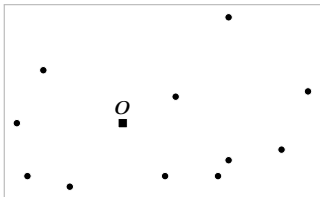
Capacitated Vehicle Routing Problem (CVRP)

Input:

- depot
- set of terminals
- capacity k



Minimize total length of tours



Fundamental problem in operations research

Unit Demand



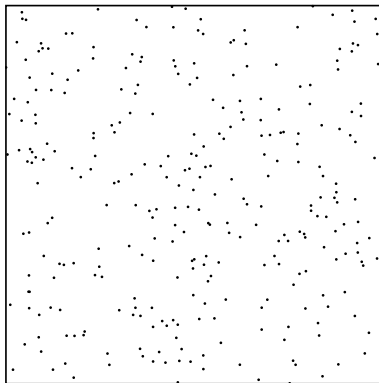
Unsplittable Demand



- general metrics
- Euclidean plane
- trees
- planar graphs
- graphs of bounded treewidth
- graphs of bounded highway dimension
- graphic metrics

Random Setting in the Euclidean Plane

Terminals: **independent, identically distributed** random points in $[0, 1]^2$



CVRP in the Random Setting

Previous results

- 2-approximation [Haimovich and Rinnooy Kan 1985]
- 1.995-approximation [Bompadre, Dror, and Orlin 2007]
- 1.915-approximation [Mathieu and Z. 2022]

New results

- 1.55-approximation [this work]

CVRP in the Random Setting: Our Results

Theorem

Sweep algorithm is at most 1.55-approximation.

Sweep algorithm

- 1 **Sort** terminals according to the **polar angle** w.r.t. the depot O
- 2 Partition terminals into groups, each of k/ϵ **consecutive terminals**
- 3 For each group, compute a $(1 + \epsilon)$ -**approximate solution**

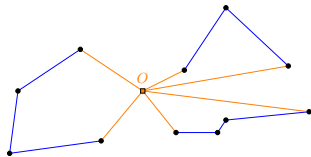
Conjecture

Sweep algorithm is $(1 + \epsilon)$ -approximation.

Analysis: Warm Up [Haimovich and Rinnooy Kan 1985]

Two factors in the solution cost:

- ① traveling salesman tour cost **TSP**
- ② radial cost **rad** $:= \frac{2}{k} \cdot \sum_v \delta(O, v)$



Properties on the optimal cost **OPT**:

- $\mathbf{OPT} \geq \mathbf{rad}$
- $\mathbf{OPT} \geq \mathbf{TSP}$

Implication: **2-approximation algorithm**

Analysis: Our Approach in High Level

Generalization of radial cost and TSP cost

For a real value R :

- $\text{rad}(R) := \frac{2}{k} \sum_v \min \{ \delta(O, v), R \}$
- $\text{TSP}(R) := \text{TSP cost on } \{v : \delta(O, v) \geq R\}$

Structure Theorem

$$\text{OPT} \geq \text{rad}(R) + \text{TSP}(R).$$

Implications:

- $R = 0 \implies \text{OPT} \geq \text{TSP}$
- $R = \infty \implies \text{OPT} \geq \text{rad}$
- R well chosen:

Theorem

Sweep algorithm is at most 1.55-approximation.

Proof of the Structure Theorem

Structure Lemma

Consider a tour S . Let V_S denote the set of points visited by S . Let C be the circle centered at O and with radius R . Let T denote the intersection between S and the exterior of C . Then

$$\text{length}(S) \geq \frac{2}{k} \sum_{v \in V_S} \min \{ \delta(O, v), R \} + \text{length}(T).$$



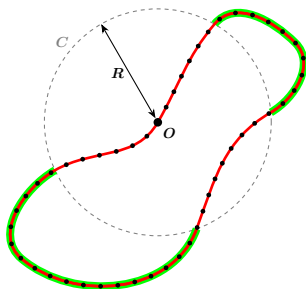
summing over all tours
in an optimal solution

Structure Theorem

$$\text{OPT} \geq \text{rad}(R) + \text{TSP}(R).$$

Proof of the Structure Lemma (1/2)

Case 1: $T \neq \emptyset$.



S : in red
 T : in green

We have

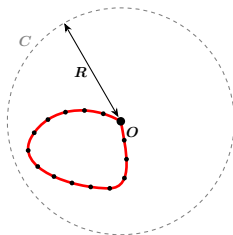
$$\text{length}(S) \geq 2R + \text{length}(T),$$

where

$$2R = \frac{2}{|V_S|} \sum_{v \in V_S} R \geq \frac{2}{k} \sum_{v \in V_S} \min \{ \delta(O, v), R \}.$$

Proof of the Structure Lemma (2/2)

Case 2: $T = \emptyset$.



S : in red

We have

$$\text{length}(S) \geq 2 \cdot \max_{v \in V_S} \delta(O, v) \geq \frac{2}{|V_S|} \sum_{v \in V_S} \delta(O, v) \geq \frac{2}{k} \sum_{v \in V_S} \min \{ \delta(O, v), R \}.$$



Cost of Sweep Algorithm: Sol

Sweep algorithm

- 1 **Sort** terminals according to the **polar angle** w.r.t. the depot O
- 2 Partition terminals into groups, each of k/ε **consecutive terminals**
- 3 For each group, compute a $(1 + \varepsilon)$ -**approximate solution**

Remark

If optimal cost of CVRP is linear with respect to **angular partitioning**, then the sweep algorithm provides a $(1 + \varepsilon)$ -approximation.

Upper bound [Haimovich and Rinnooy Kan 1985] for CVRP:

$$\mathbf{OPT} \leq \mathbf{rad} + \mathbf{TSP}.$$

TSP is linear with respect to **angular partitioning**, as a corollary of Richard Karp's result, so we have:

Upper Bound on Sol

$$\mathbf{Sol} = \sum \mathbf{OPT}_i \leq \sum \mathbf{rad}_i + \sum \mathbf{TSP}_i \approx \mathbf{rad} + \mathbf{TSP}.$$

Main Theorem: 1.55-Approximation

New Upper Bound on Approximation Ratio

$$\frac{\text{Sol}}{\text{OPT}} \leq 1.55.$$

Proof:

$$\begin{aligned} \frac{\text{Sol}}{\text{OPT}} &\leq \min_R \frac{\text{rad} + \text{TSP}}{\text{rad}(R) + \text{TSP}(R)} \\ &\leq \min_R \max \left(\frac{\text{rad}}{\text{rad}(R)}, \frac{\text{TSP}}{\text{TSP}(R)} \right) \\ &\leq 1.55. \end{aligned}$$

Converting to Continuous Form

Let v be a uniformly random point in the unit square.

Discrete	Continuous
rad	$\frac{2n}{k} \mathbb{E}(\delta(O, v))$
rad(R)	$\frac{2n}{k} \mathbb{E}(\min(\delta(O, v), R))$
TSP	$\beta\sqrt{n}$
TSP(R)	$\beta\sqrt{n} \mathbb{P}(\delta(O, v) \geq R)$

We choose

$$R = \frac{3}{4} \mathbb{E}(\delta(O, v)).$$

Two-variable inequalities

Lemma

Let $R = \frac{3}{4} \mathbb{E}(\delta(O, v))$, then

$$\mathbb{E}(\delta(O, v)) < 1.55 \mathbb{E}(\min(\delta(O, v), R)),$$

$$1 < 1.55 \mathbb{P}(\delta(O, v) \geq R).$$

Linear in the distribution of $v \rightarrow$ Partition the square and the disk $\{p : \delta(O, p) \leq R\}$ into **disk sectors** and **triangles**.

Closed-Form Formula [Stone 1991]

$$\int_0^a \int_0^{\frac{bx}{a}} \sqrt{x^2 + y^2} dy dx = \frac{a^3}{6} \log \left(\frac{b}{|a|} + \sqrt{1 + \frac{b^2}{a^2}} \right) + \frac{ab}{6} \sqrt{a^2 + b^2}.$$

Thank you!