## **Density estimation in Total Variation**

Let  $(X_1, \ldots, X_n)$  be an independent sample with marginals  $P_1^{\star}, \ldots, P_n^{\star}$ . Let

$$\overline{P}^{\star} = \frac{1}{n} \sum_{i=1}^{n} P_i^{\star}.$$

The aim is to estimate  $\overline{P}^{\star}$  using the sample. Error is quantified using total variation distance

$$d_{TV}(P,Q) = \sup_{A \in \mathcal{B}(\mathbb{R})} |(P-Q)(A)|$$

A shape constraint is assumed for  $\overline{P}^{\star}$  and imposed on the estimator  $\hat{P}$ , associated to a density model such as

$$\begin{split} \mathcal{M}^{cv}(I) &= \{ \texttt{p} \text{ is convex on } I = \texttt{supp}(p) \} \\ \mathcal{M}^{cv} &= \bigcup \{ \mathcal{M}^{cv}(I) : I \text{ interval} \} \\ \mathcal{M}^{dec}(I) &= \{ \texttt{p} \text{ is non-increasing on } I = \texttt{supp}(p) \} \\ \mathcal{M}^{dec} &= \bigcup \{ \mathcal{M}^{cv}(I) : I \text{ interval} \} \\ \mathcal{M}^{lcv} &= \{ p = e^{\phi}, \phi : \mathbb{R} \to \mathbb{R} \cup \{ -\infty \} \text{ concave} \} \end{split}$$

## Motivation

Maximum likelihood (ML) is by far the most popular approach in the field. However, ML

• is **undefined** on  $\mathcal{M}^{cv}$ ,  $\mathcal{M}^{dec}$  (support <u>must be known</u>)

- Fails to be robust
  - to model mis-specification
  - or to outliers.

Our estimator overcomes these shortcomings of maximum likelihood.

#### **TV-estimation**

For any two pdfs p, q, let

$$t_{p,q} = 1 |_{q > p} - \int_{\{q > p\}} p(x) dx.$$

Given a sample  $\mathbf{X} = (X_1, \ldots, X_n)$ , let

$$T(\mathbf{X}, p, q) = \frac{1}{n} \sum_{i=1}^{n} t_{p,q}(X_i).$$

Given in addition a countable *density model*  $\mathcal{M}$ , let

$$T_{\mathcal{M}}(\mathbf{X}, p) = \sup_{q \in \mathcal{M}} T(\mathbf{X}, p, q).$$

A TV-estimator associated with the model  $\mathcal{M}$  and precision  $\varepsilon$  is some  $\hat{p}_{\mathcal{M}} \in \mathcal{M}$ s.t.

$$T_{\mathcal{M}}(\mathbf{X}, \hat{p}_{\mathcal{M}}) \leq \inf_{p \in \mathcal{M}} T_{\mathcal{M}}(\mathbf{X}, p) + \varepsilon.$$

Let also  $\hat{P}_{\mathcal{M}} : A \mapsto \int_A \hat{p}_{\mathcal{M}}(x) dx$ .

# ROBUST ESTIMATION IN TOTAL VARIATION DISTANCE UNDER A SHAPE CONSTRAINT Yannick Baraud, Hélène Halconruy, <u>Guillaume Maillard</u> University of Luxembourg

# Extremal point of a model

 $\overline{p} \in \mathcal{M}$  is *extremal in*  $\mathcal{M}$  with degree at most D ( $\overline{p} \in \mathcal{O}(D)$ ) if

- $\{\{q > \overline{p}\} : q \in \mathcal{M}\}$  is VC with dimension  $\leq D$
- $\{\{q < \overline{p}\} : q \in \mathcal{M}\}$  is VC with dimension  $\leq D$ .

#### For example,

- In  $\mathcal{M}^{dec}$ , if p is piecewise constant with D pieces, then  $p \in \mathcal{O}(3D+9)$
- In  $\mathcal{M}^{cv}$ , if p is piecewise affine with D pieces, then  $p \in \mathcal{O}(2D + 10)$ .

## **Properties of** $\hat{p}_{\mathcal{M}}$

**Theorem 1.** For any  $p \in \mathcal{M}$ , let

$$\mathbb{B}_{(n)}(P) = \inf_{D \ge 1} \left\{ 3 \inf_{P \in \mathcal{O}(D)} d_{TV}(\overline{P}^{\star}, P) + 48\sqrt{\frac{D}{n}} \right\}.$$

For any  $\xi > 0$ , with probability greater than  $1 - e^{-\xi}$ ,

$$\mathbb{E}\left[d_{TV}\left(\hat{P}_{\mathcal{M}}, \overline{P}^{\star}\right)\right] \leq \mathbb{B}_{n}(\overline{P}^{\star}) + \sqrt{\frac{2(\log 2 + \xi)}{n}} + \frac{\varepsilon}{n}.$$

Hence,  $\hat{P}_{\mathcal{M}}$ 

- converges at parametric rate  $\sqrt{\frac{D}{n}}$  if  $\overline{P}^{\star} \in \mathcal{M}$  (Adaptivity)
- Is robust
  - To mis-specification: if  $\overline{P}^{\star} \notin \mathcal{M}, \overline{P} \in \mathcal{M},$

$$\mathbb{B}_n(\overline{P}^{\star}) \le \mathbb{B}_n(\overline{P}) + 3d_{TV}(\overline{P}^{\star}, \overline{P}).$$

- To outliers: let  $P_i^{\star} = \overline{P}, i \in I$  and  $P_i^{\star} = Q_i, i \in O$ , then  $I = (\overline{D}^{\star}, \overline{D}) < \frac{1}{2} \sum_{n \in \mathbb{N}} I = (O, \overline{D}) < |O|$ 

$$d_{TV}\left(P^{\uparrow},P\right) \leq \frac{1}{n} \sum_{i \in O} d_{TV}(Q_i,P) \leq \frac{1}{n}$$

It follows that

$$\mathbb{B}_n(\overline{P}^\star) \le \mathbb{B}_n(\overline{P}) + 3\frac{|O|}{n},$$

i.e the upper bound increases at most by  $3\frac{|O|}{n}$ .

## **Convergence rates**

Let  $\overline{P}^{\star}$  have pdf  $\overline{p}^{\star}$ . Let

$$I = \operatorname{supp}(\overline{p}^{\star}), L = |I|, V = \sup_{I} \overline{p}^{\star} - \inf_{I} \overline{p}^{\star}.$$

Assuming  $\overline{p}^{\star} \in \mathcal{M}$ , we obtain the following rates.

$$\begin{array}{|c|c|c|c|c|} \mbox{Model }\mathcal{M} & \mathbb{E}\left[d_{TV}\left(\hat{P}_{\mathcal{M}},\overline{P}^{\star}\right)\right] \leq & \mbox{Optimal?} \\ \mbox{$\mathcal{M}=\mathcal{M}^{dec}$} & c_1\left(\frac{\log(1+VL)}{n}\right)^{1/3} + \frac{c_2}{\sqrt{n}} & \mbox{Yes} \\ \mbox{$\mathcal{M}=\mathcal{M}^{cv}$} & c_1\left(\frac{\log(1+\sqrt{VL})}{n}\right)^{2/5} + \frac{c_2}{\sqrt{n}} & \mbox{Best know} \\ \mbox{$\mathcal{M}=\mathcal{M}^{lcv}$} & \frac{c_1}{n^{2/5}} & \mbox{Yes} \\ \end{array}$$

where  $c_1, c_2$  are numerical constants.

## Conclusion

The following table shows how TV-estimation compares to alternatives on the different models.

Property	TV-estimator	MLE	$\rho-\text{estimator}[1]$
Defined	All	$\mathcal{M}^{dec}(I), \mathcal{M}^{lcv}$	All
Robust	All	$\mathcal{M}^{dec}(I)$ no, $\mathcal{M}^{lcv}$ ?	All
Adaptive	All	$\mathcal{M}^{dec}(I)$ [2], $\mathcal{M}^{lcv}$ [5]	$\mathcal{M}^{dec}, \mathcal{M}^{lcv}$
Optimal	All	$\mathcal{M}^{dec}(I)$ [2], $\mathcal{M}^{lcv}$ [4]	$\mathcal{M}^{dec}$ (rate)

# Bibliography

#### References

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In Piec. Poly [3]  $\mathcal{M}^{lcv}$  $|\mathcal{M}^{lcv}|$ No  $\mathcal{M}^{lcv}$